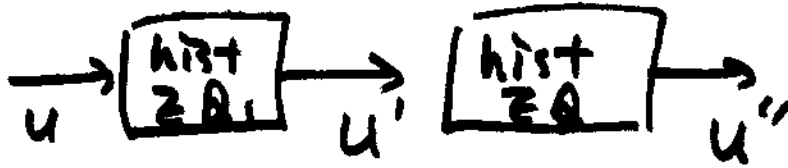


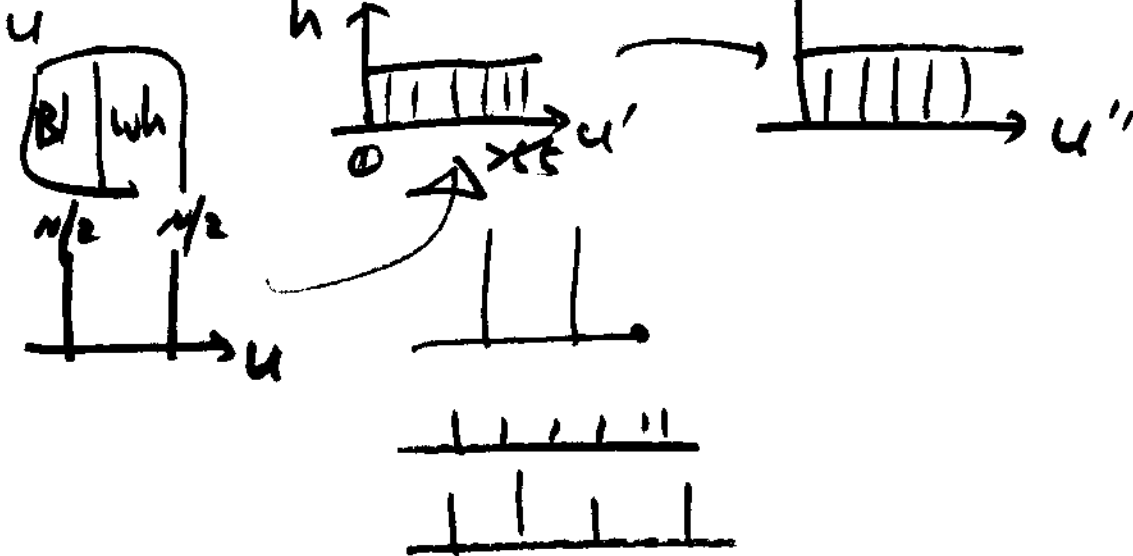
EE 4830 March 24th '05 - Lecture 8

Midterm Solutions

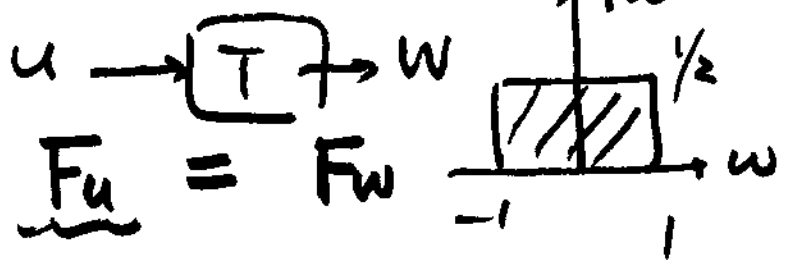
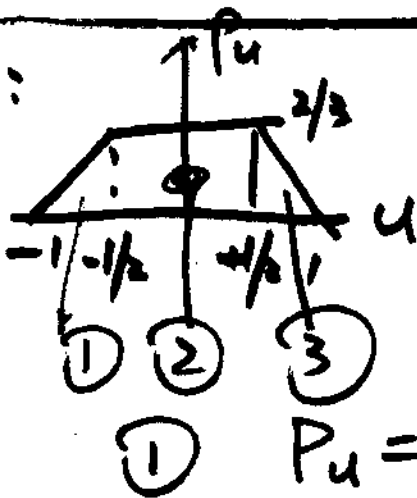
P1:



$u' = u'' ?$



P2:

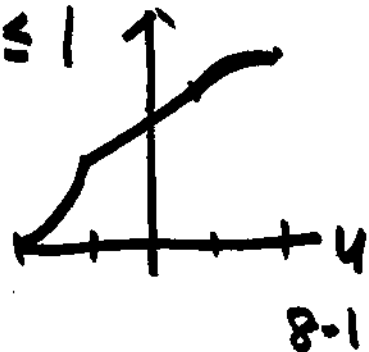


$$P_u = \begin{cases} \frac{4}{3}(u+1) & -1 \leq u < -\frac{1}{2} \\ \frac{2}{3} & -\frac{1}{2} \leq u < \frac{1}{2} \\ \frac{4}{3}(u-1) & \frac{1}{2} \leq u \leq 1 \end{cases}$$

CDF

$$F_u = \begin{cases} \frac{2}{3}u^2 + \frac{4}{3}u + \frac{1}{3} & \text{(1)} \\ \frac{1}{3}u + \frac{1}{2} & \text{(2)} \\ \frac{2}{3}u^2 + \frac{4}{3}u + \frac{1}{3} & \text{(3)} \end{cases}$$

(1)
(2)
(3)



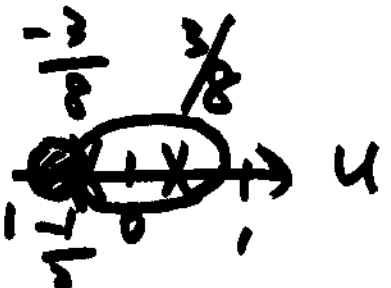
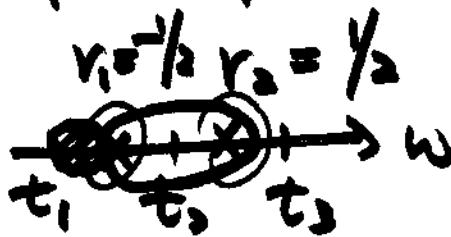
$$F_w(w) = \frac{w+1}{2}$$

$$F_u = F_w$$

$$w = \frac{\frac{4}{3}u^2 + \frac{8}{3}u + \frac{1}{3}}{\frac{4}{3}u^2 + \frac{8}{3}u - \frac{1}{3}}$$

① $u \in (-1, \frac{1}{3})$
 ② w
 ③ \checkmark

2-step Q for w



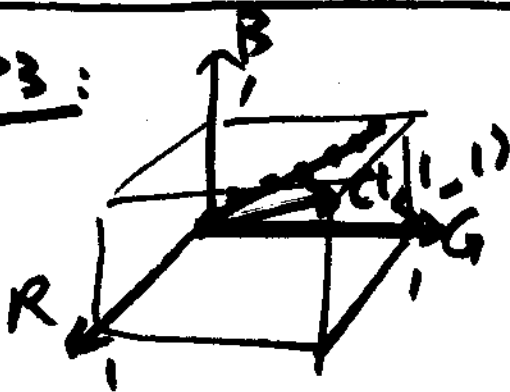
$$w = \frac{4}{3}u$$

$$u = \frac{3}{4}w = \frac{3}{4}(\pm \frac{1}{2}) = \pm \frac{3}{8}$$

$$\frac{4}{3} \cdot (\frac{1}{2})^2 + \frac{8}{3}(\frac{1}{2}) + \frac{1}{3}$$

$$= \frac{1}{3} + \frac{4}{3} + \frac{1}{3} = \frac{6}{3} = 2$$

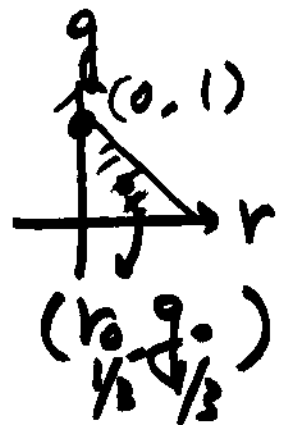
P3:



$$r = \frac{R}{(R+G+B)}$$

$$g = \frac{G}{(R+G+B)}$$

$$b = \frac{B}{(R+G+B)}$$

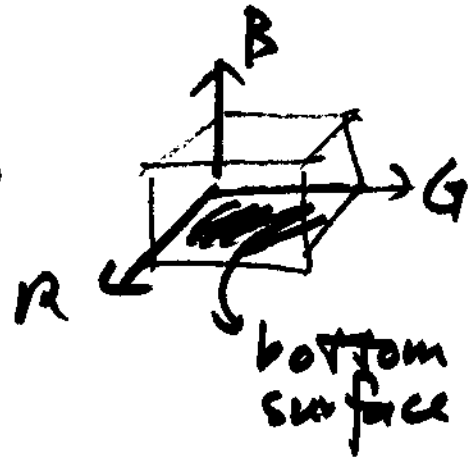
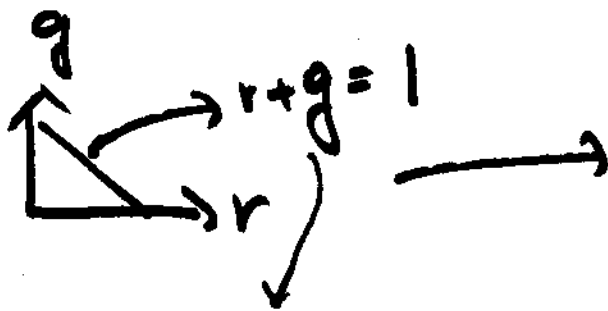


(a) $r = r_0 = \frac{R}{(R+G+B)}$

$$\Rightarrow (1-r_0)R - r_0 \cdot G - r_0 \cdot B = 0$$

$$g_0 = \frac{G}{R+G+B} \Rightarrow -g_0 \cdot R + (1-g_0)G + g_0 \cdot B = 0$$

(b)

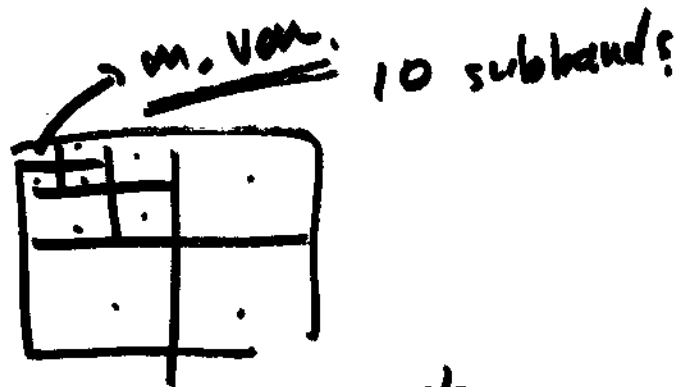
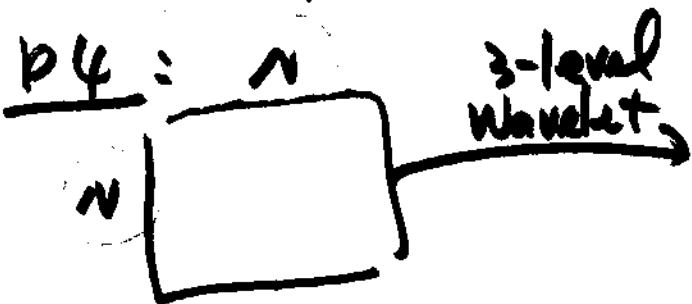
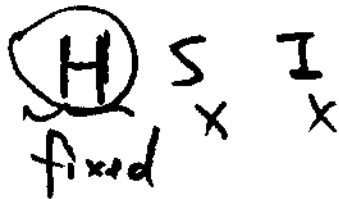


$$\frac{R}{R+G+B} + \frac{G}{R+G+B} = 1$$

$$\Rightarrow B = 0$$

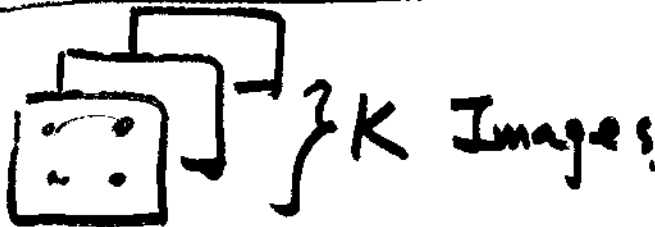
(c) a point in $\begin{matrix} g \\ \updownarrow \\ r \end{matrix} \Rightarrow$ unique HSI?

From part (a) \Rightarrow a line in RGB space.



$$\vec{u} = (m_{11}, v_{12}, \dots, z_0)^T \quad 20 \times 1$$

$$\vec{u}_i = (u(i), u(i), \dots, u(i))$$



$$R_u(i, j) \quad 20 \times 20 = E((u(i) - m)(u(j) - m)) = \sum_{k=1}^K (u_k(i) - m)(u_k(j) - m)$$

$$A = \begin{bmatrix} \vec{u}_1 & \vec{u}_2 & \dots & \vec{u}_K \end{bmatrix}$$

$20 \times K$ 20×1 20×1 20×1

De-Mean $\vec{u}' = \vec{u} - \bar{m}$

$$A' = [\vec{u}'_1 \quad \vec{u}'_2 \quad \dots \quad \vec{u}'_K]$$

20×1

$$R_{20 \times 20} = \underbrace{A'}_{20 \times K} \underbrace{A'^T}_{K \times 20}$$

Find eigenvector $\vec{\phi}_1 \dots \vec{\phi}_{20}$ assuming $K > 20$

$$\Phi = [\vec{\phi}_1 \quad \vec{\phi}_2 \quad \dots \quad \vec{\phi}_{20}]$$

20×20

KLT

I KLT

$$\vec{v} = \Phi^T \vec{u}$$

$$\vec{u} = \Phi \vec{v}$$

$\rightarrow \text{corr.} \approx 1$

(Bonus) $\vec{u} = [0 \quad 0 \quad 1 \quad 0 \quad 0 \quad 0 \quad 0]$

$\sqrt{3}$ cols = 1

\downarrow KLT, I KLT (subset of eigen. vectors)

$$\vec{u}' = [0.2 \quad 0.4 \quad 0.9 \quad 0.3 \quad 0.1]$$

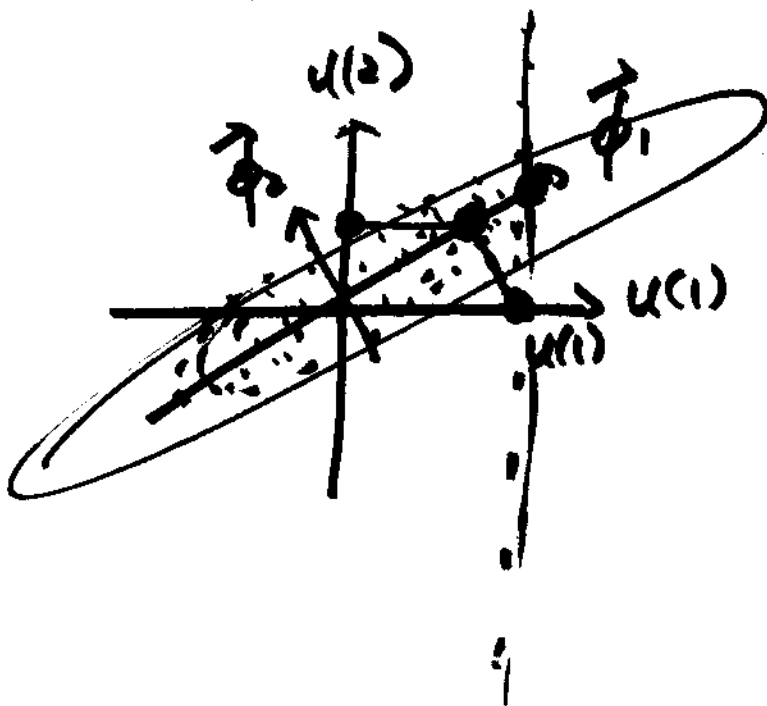
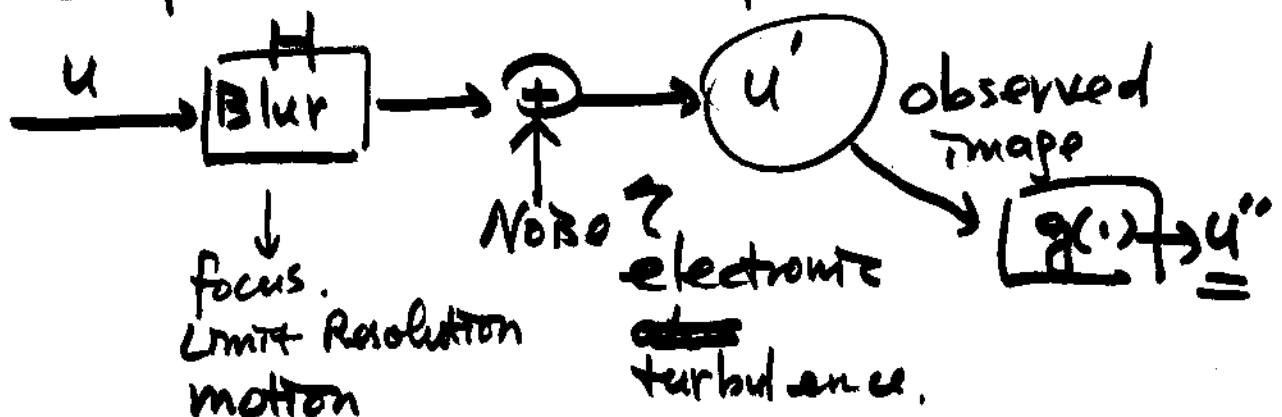


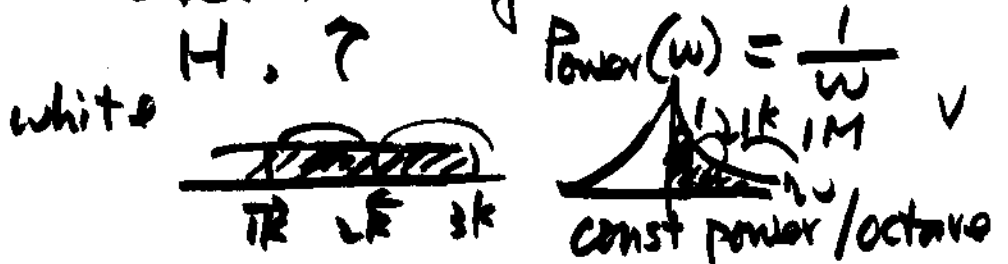
Image Restoration
 Chap 5 G8W . Chap 8 Jath.



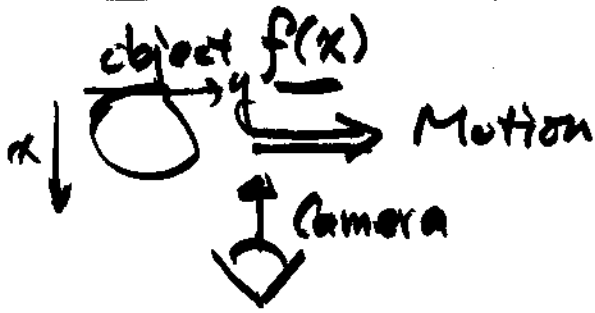
Quality Degradation

Earlier : Hist. Egu.
 Contrast Enhancement
 Edge Sharpening) Per Image

Here : model the degradation sources



Motion Blur



trajectory
 $x(t) = a \cdot t \quad t = 0 \dots T$
 speed

T : duration of imaging process
 shutter open

$$f(x, t) = f(x - at)$$

a : #pixels/sec
 ms.

$$g(x) = \int_{t=0}^T f(x - at) dt$$

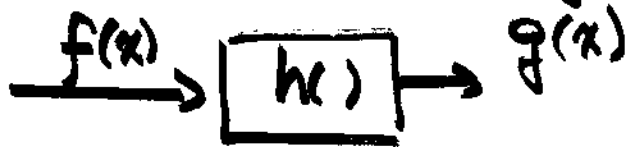
"Blur Effect"

observed
 Im

Instantaneous
 Input



Estimate the effect by using Filter H



$$F(\omega) \cdot H(\omega) = G(\omega)$$

transfer function

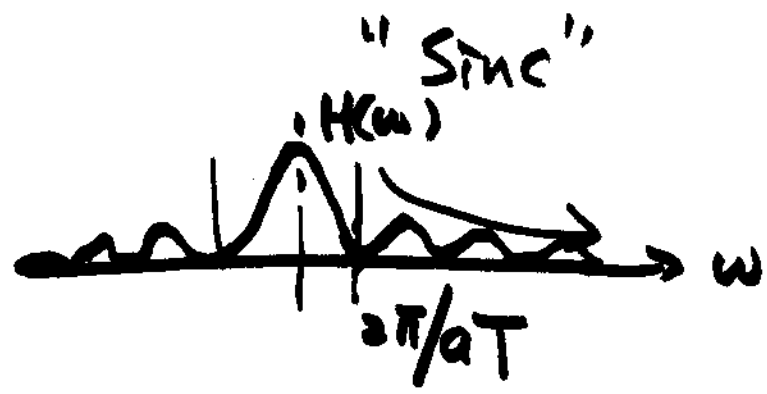
F.T on $*$

$$G(\omega) = \int_{-\infty}^{\infty} \underbrace{\int_{t=0}^T f(x - at) dt}_{g(x)} e^{-j\omega x} \cdot dx$$

$$= F(\omega) \left(\int_0^T e^{-j\omega at} dt \right)$$

For your exercise.

$$H(\omega) = \frac{2}{a \cdot \omega} \text{Sinc}\left(\frac{\omega a T}{2}\right) e^{-\frac{j \omega a}{2}}$$



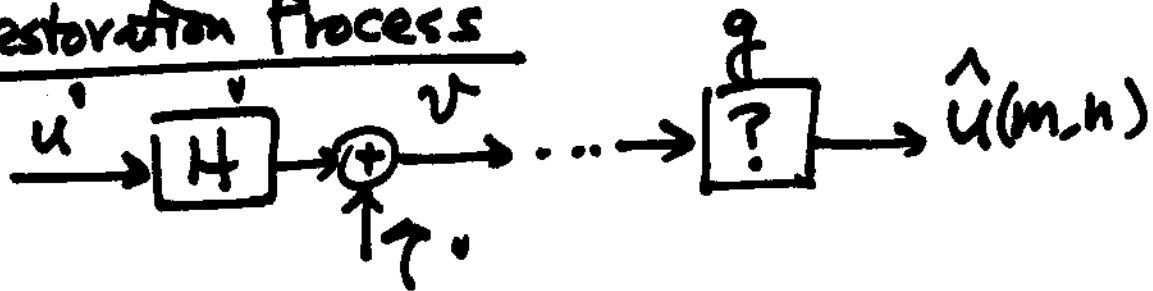
- $I \uparrow \Rightarrow$ Narrow BW
- \Rightarrow More Blur
- $a \uparrow \Rightarrow$ faster motion
- $\hookrightarrow H$

$H = f_{\text{special}}(\text{'motion'}, \frac{\text{Len.}}{50}, \frac{\text{Ang}}{45^\circ})$
 \hookrightarrow vector
 50 pixels
 $a \cdot T$

$$I = \text{Imread}(\dots)$$

$$I' = \text{imfilter}(I, H)$$

Restoration Process



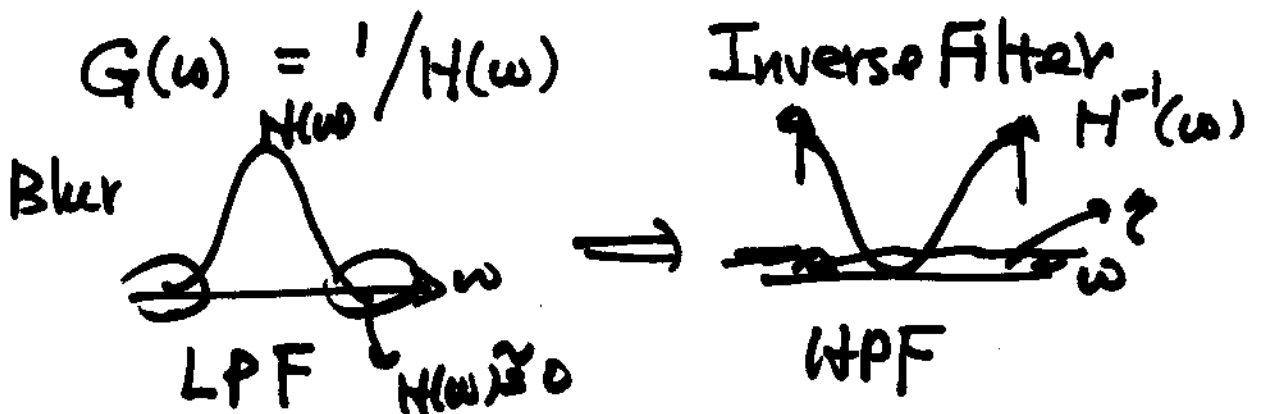
Freq. Domain

$$V(\omega) = U(\omega) \cdot H(\omega) + \underline{\underline{z(\omega)}}$$

Simple Case: $\underline{\underline{z=0}}$

$$V(\omega) = U(\omega) \cdot H(\omega)$$

$$G(\omega) = 1/H(\omega)$$



In practice, $z \neq 0$

$H(\omega) \approx 0 \Rightarrow 1/H$ large, amplify noise.

Pseudoinverse Filter

$$H^{-1}(\omega) = \begin{cases} 1/H & H \neq 0 \\ 0 & H \approx 0 \end{cases}$$

MSE (Min. Squared Error) Linear Estimator.

Find the optimal \hat{u}

s.t.
$$\text{MSE} = E[(u - \hat{u})^2]$$
 is minimized

given the knowledge of

H ,

u → Autocorrelation

γ → Autocorrelation

Wiener Filter

$$G_{\text{opt}}(\omega) = \frac{H^*(\omega) S_{uu}(\omega)}{|H(\omega)|^2 S_{uu}(\omega) + S_{\gamma\gamma}(\omega)}$$

PSD of random sequence
Power spectral distribution

Dif $\gamma = 0$

$$G_{\text{opt}}(\omega) = 1/H(\omega) \quad \text{Inverse Filter}$$

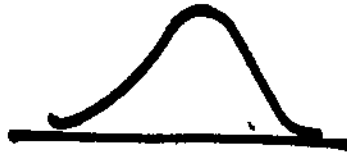
$$|H(\omega)|^2 = H \cdot H^*$$

② No Blur $H(\omega)$: All Pass Filter

$$\begin{aligned} G_{\text{opt}}(\omega) &= \frac{S_{uu}(\omega)}{S_{uu}(\omega) + S_{\gamma\gamma}(\omega)} \\ &= \frac{1}{1 + (S_{\gamma\gamma}/S_{uu})} = \frac{1}{1 + \text{SNR}^{-1}} \end{aligned}$$

③ General

$H \neq 1$



LPF

$\tau \neq 0$



white noise

~~SFF~~
Su4



Q: what does $G(\omega)_{opt}$ look like ?

