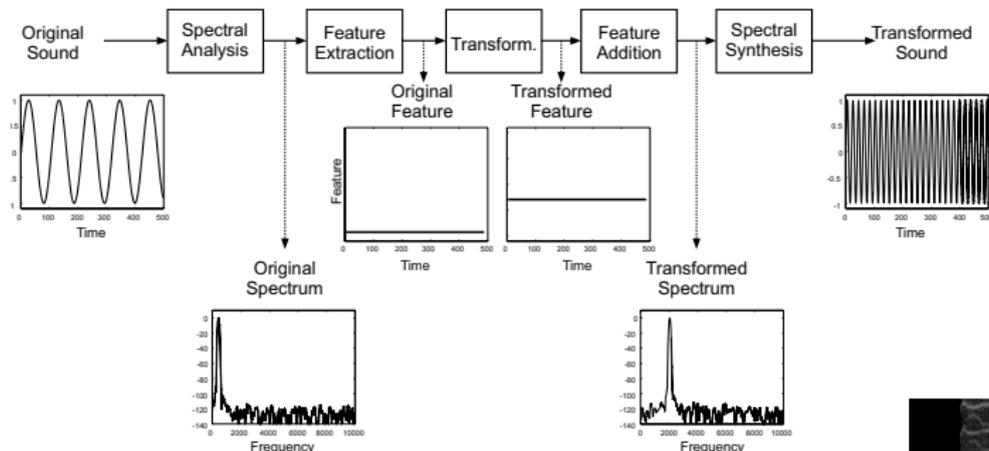


# E85.2607: Lecture 9 – Sinusoidal Modeling

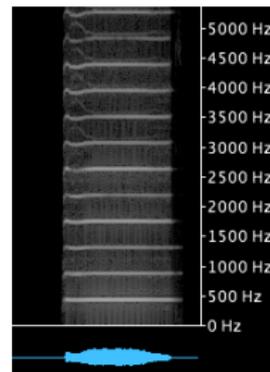
# Sinusoidal Modeling/Spectral Modeling Synthesis (SMS)



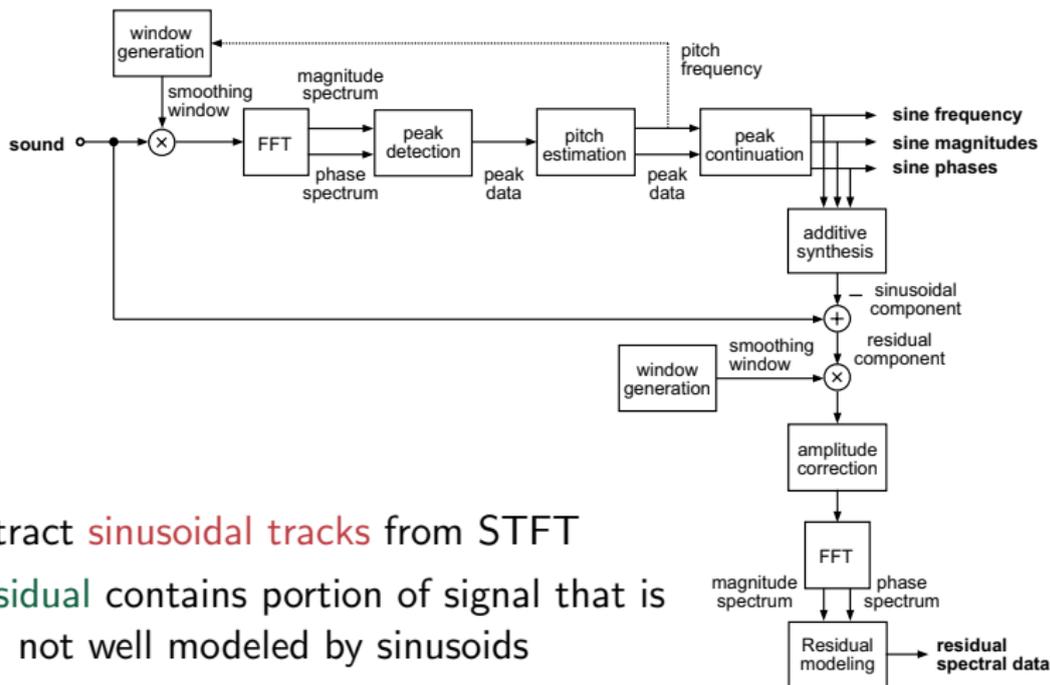
- Similar to phase vocoder, but assumes that signal is sum of sinusoids with smoothly varying parameters:

$$x[n] \approx \tilde{x}[n] = \sum_k a_k[n] \cos(\omega_k[n])$$

- Freq. domain representation analogous to **Fourier series**
- Flexible representation for transformations...



# SMS overview



## Analysis

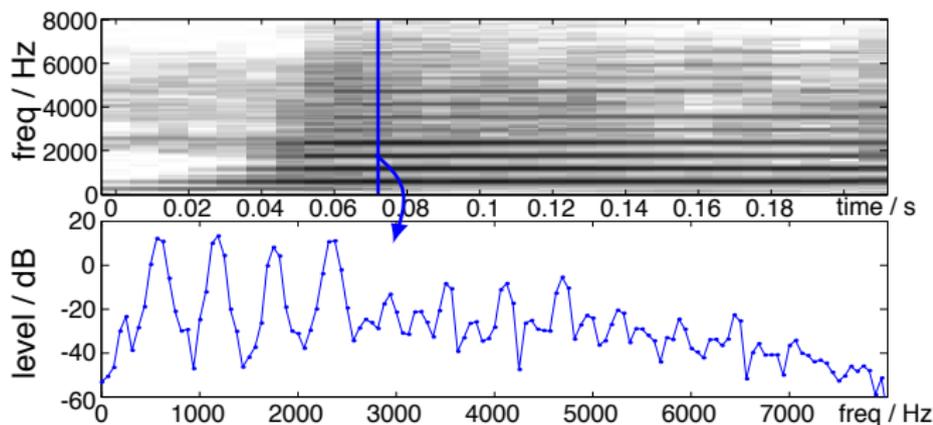
Extract **sinusoidal tracks** from STFT

**Residual** contains portion of signal that is not well modeled by sinusoids

## Synthesis

Each track controls an oscillator

# Analysis overview



- 1 Break signal into frame ala STFT
  - Be aware of time-frequency tradeoff
- 2 Pick peaks in each frame
  - Often expect to find peaks in harmonic series due to common pitch
  - Search for common factor
- 3 Organize spectral peaks into time-varying sinusoidal tracks
  - Expect sinusoids to drift in amplitude and frequency

# Review: Time-frequency tradeoff

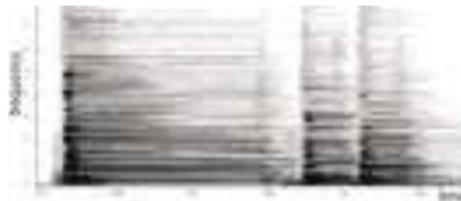
$$X[k, m] = \sum_{n=0}^{N-1} x[n + mL] w[n] e^{-j \frac{2\pi kn}{N}}$$

DFT length  $N$

- Window determines freq. resolution
- Must be long enough to resolve harmonics  
 $\sim 2 \times$  longest pitch period ( $\sim 50 - 100$  ms)
- Too long  $\rightarrow$  blurred  $a_k[n]$

Hop size  $L$

- typically  $N/2$  or  $N/4$
- small hop  $\rightarrow$  simpler interpolation over time

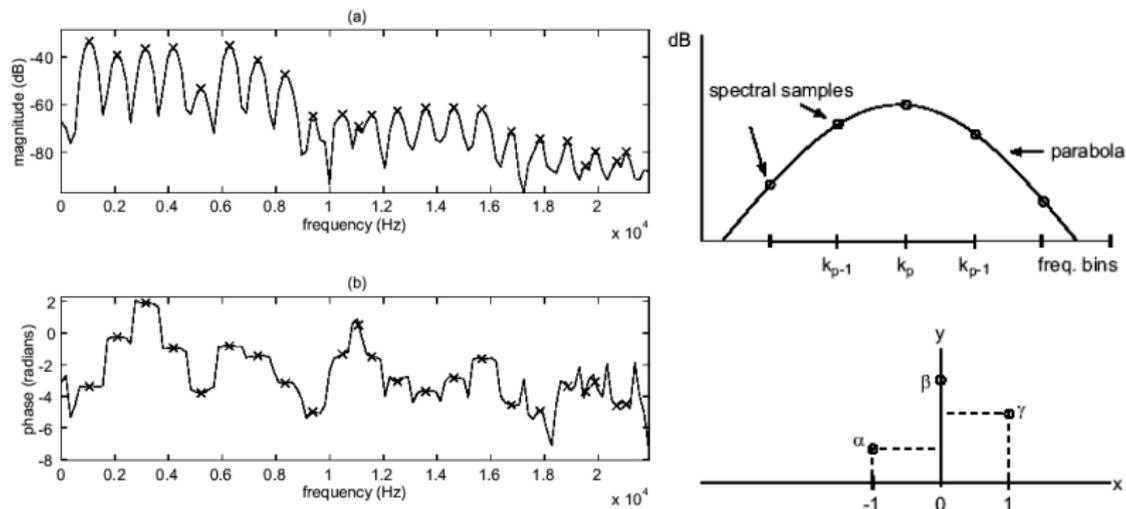


good freq. resolution  
bad time resolution



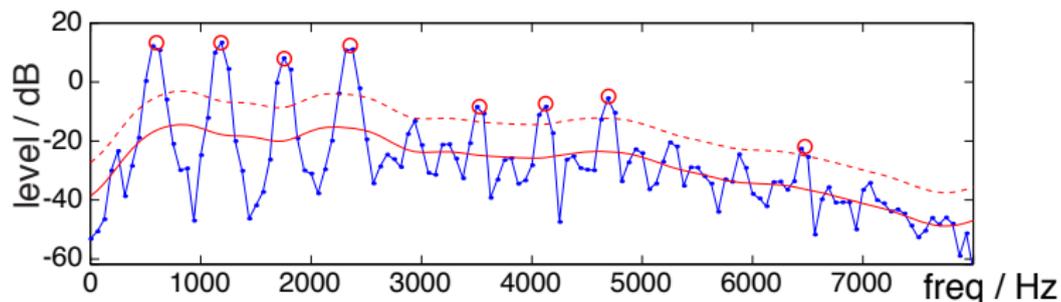
bad freq. resolution  
good time resolution

# Peak picking



- Find local maxima in each DFT frame
- Accuracy of peak detection is limited to half a sample
  - Can zero pad, but can be expensive
- Alternative: Frequency resolution smaller than one bin using quadratic interpolation

## Peak picking 2

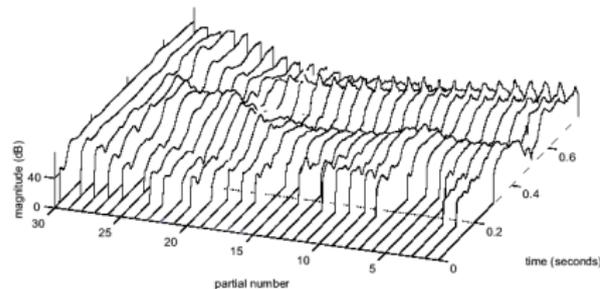
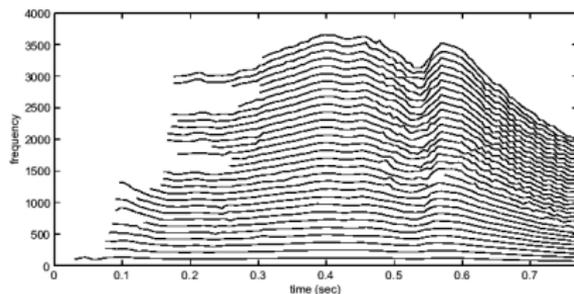


Not all peaks correspond to a stable sinusoid

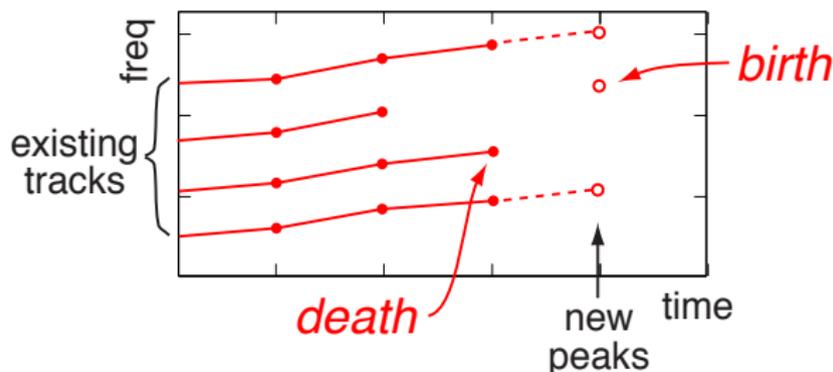
- Only retain peaks larger than some threshold
- Only retain peaks consistent with **harmonic series** of underlying pitch
  - need pitch tracker, input must be monophonic
  - pitch-synchronous analysis?
- Look for stable parameters in adjacent frames
  - e.g. stable **phase derivative** in time and frequency

# Peak continuation

- Connect peaks in adjacent frames to track sinusoid trajectory
- Lots of different approaches
  - e.g. Macaulay-Quatieri approach:  
Greedy attach peak in current frame to closest peak in next frame
- Ambiguous if large frequency changes

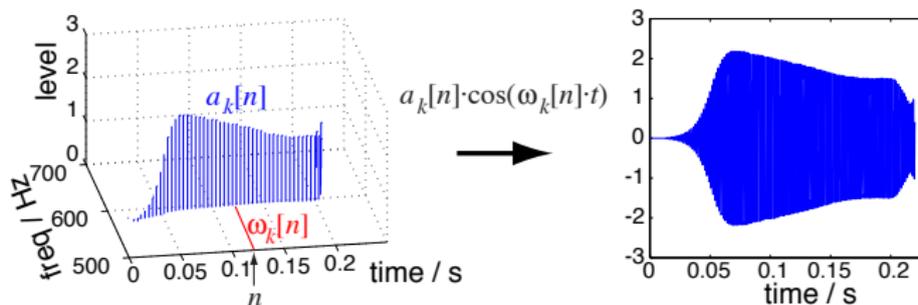


# Track formation heuristics

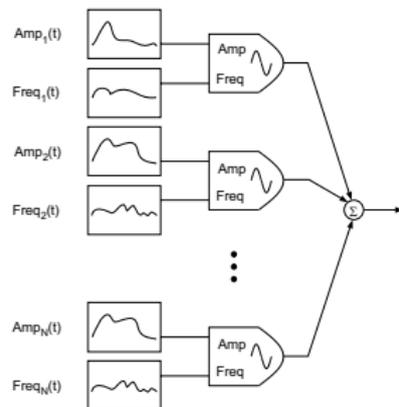


- Unclaimed peak → create **new track**
- No continuation of track → **termination**
- Lots of other potential rules:
  - min track length to avoid spurious peaks
  - max allowable frequency deviation between adjacent frames
  - max silent gap length
  - max number of tracks per frame
- Tricky to implement ...

# Sinusoidal synthesis



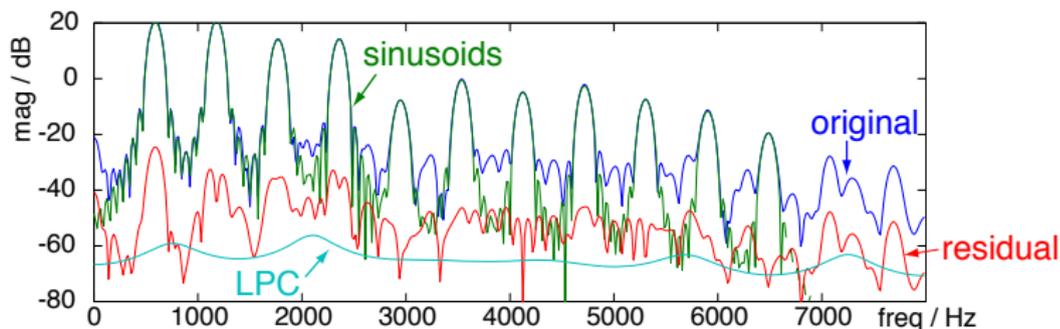
- Each sinusoid track  $\{a_k[n], \omega_k[n]\}$  drives an oscillator
- Interpolate parameters to avoid clicks at frame boundaries
- Faster method: synthesize DFT frames, then overlap-add



# Sinusoid + noise model

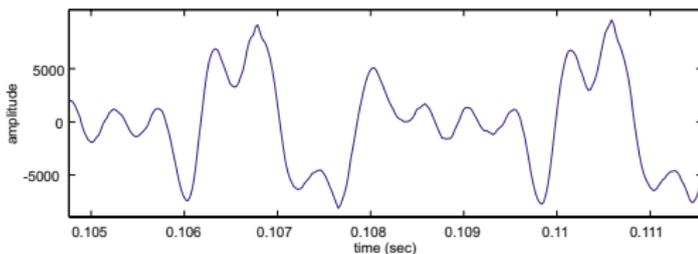
- Sinusoids is not a good fit for all types of signals (e.g. noise)
- Sometimes want to retain **residual** in addition to sinusoids

$$x[n] = \sum_k a_k[n] \cos(\omega_k[n]n) + e[n]$$

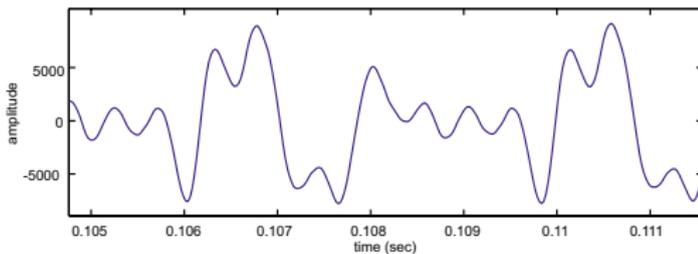


- Model residual as white noise passed through time-varying filter

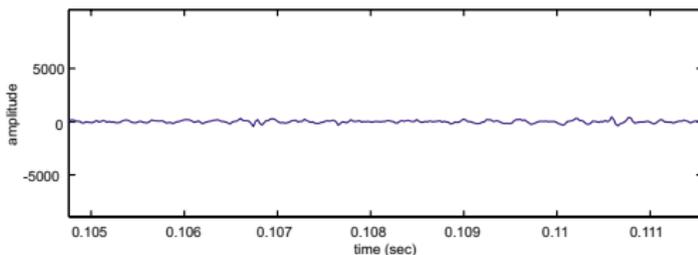
# Sinusoidal subtraction



original sound  
 $x(n)$

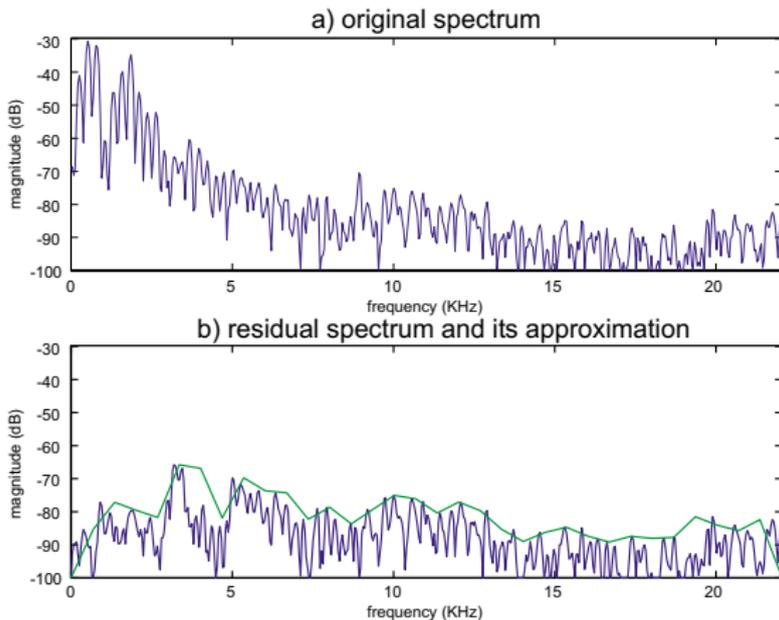


synthesized sound  
with phase matching  
 $s(n)$



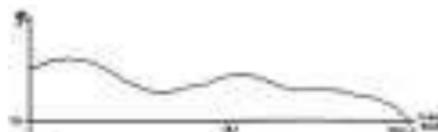
residual sound  
 $e(n) = w(n) x(n) - s(n)$ ,  
 $n = 0, 1, \dots, N - 1$

# Modeling the residual



- Many options for modeling residual filter parameters
- Can use LPC to approximate shape of residual
- or simply smooth magnitude spectrum ala channel vocoder

# Residual synthesis



spectral magnitude  
approximation of residual



random spectral phase

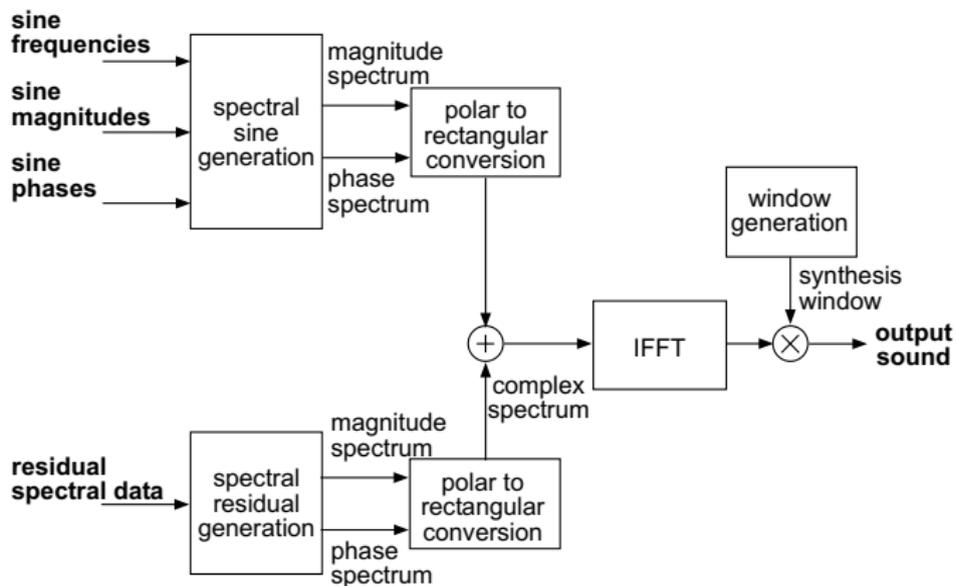


synthesized sound

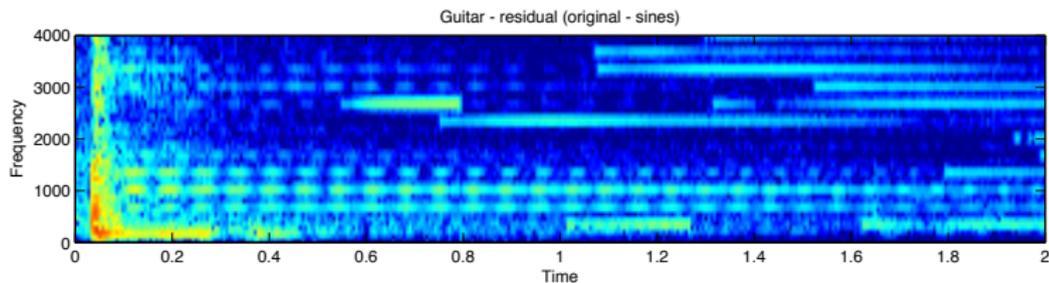
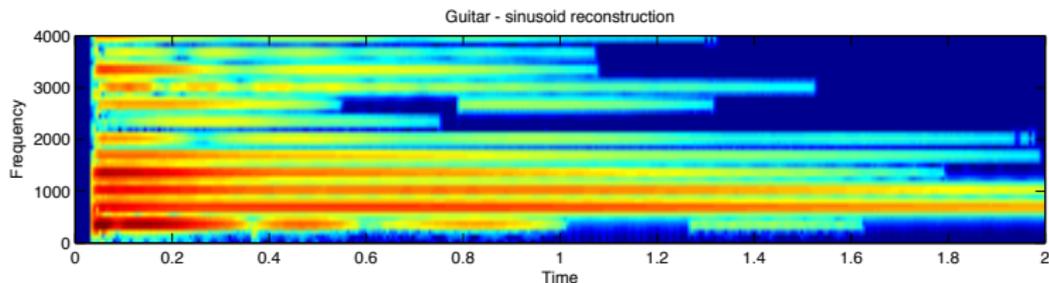
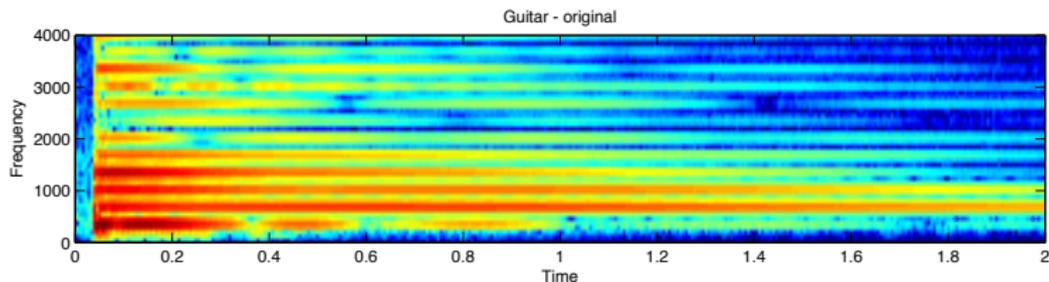


synthesized sound  
with window

# Synthesis: Putting it all together



# Sin + noise - example



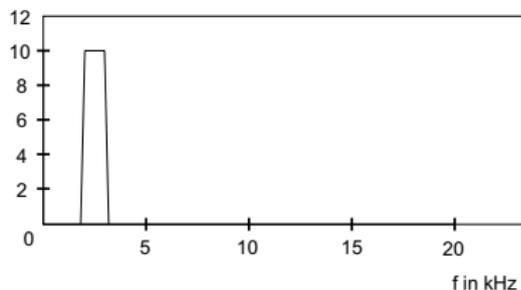
# Examples



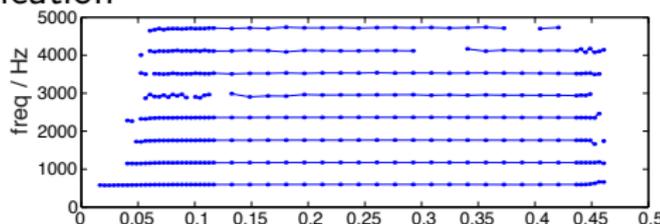
# Applications

## Loads of applications

- Similar to other TF analysis-synthesis techniques
- but parameters more convenient for some transformations
  - can treat spectral shape independent from harmonics
  - can treat different tracks independently
- Filtering with arbitrary time resolution

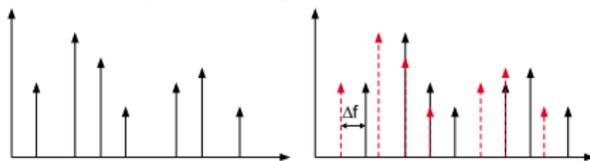


- Timescale modification



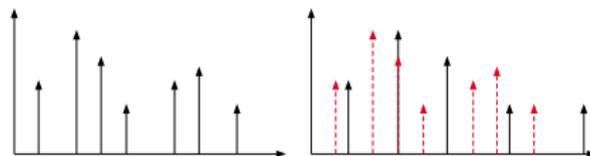
# Applications: Frequency transformations

- Partial-dependent frequency scaling



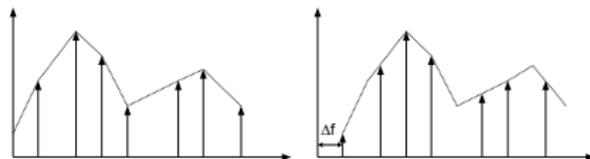
- e.g. pseudo inharmonicities of higher partials in piano sound

- Frequency stretching:  $\hat{\omega}_k[n] = p * \omega_k[n]$



- e.g. pitch-shift without preserving timbre

- Spectral shape shift



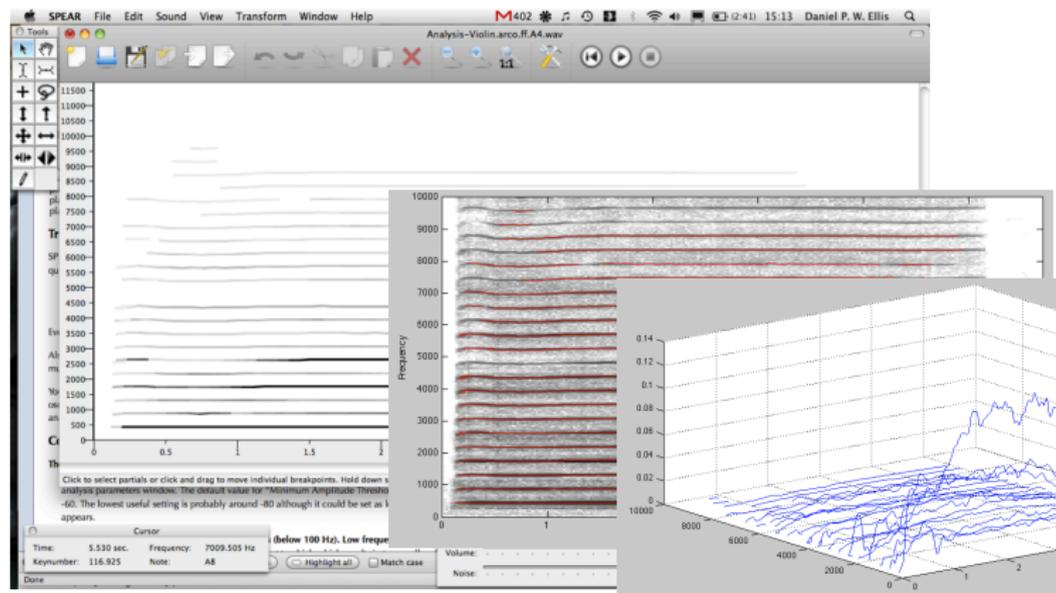
- Quantize pitch (autotune)

# Still more applications

- Effects we've seen before:
  - **Vibrato** modulate  $\omega_k[n]$  with LFO
  - **Tremolo** modulate  $a_k[n]$  with LFO
- Hoarseness: boost residual relative to sinusoidal components
- Morphing between sounds
- Gender change: shift pitch and formants separately
- Singing voice synthesis/conversion (**Vocaloid**)  
- Separate transients from steady-state harmonics   
- ...

# Tools: SPEAR

From Michael Klingbeil: <http://www.klingbeil.com/spear/>



# Bringing it all together

PVOC  $X[k, n] = A[k, n] e^{j\omega[k, n]}$

- Magnitude and phase of **fixed** oscillators

Source-filter  $X[k, n] = E[k, n] H[k, n]$

- Filter captures spectral shape (smoothed  $A[k, n]$ )
- Source is whatever is left - typically pulse train corresponding to harmonic series

Sinusoids  $X[k, n] = A_k[n] \cos(\omega_k[n]) + E[k, n]$

- Organize input into oscillators with **time-varying frequency** (harmonic tracks)
- Sinusoid magnitudes  $A_k[n]$  approximate spectral shape
- Frequencies  $\omega_k[n]$  encode source information

## DAFX Chapter 10 - Spectral Processing