EE E6820: Speech & Audio Processing & Recognition

Lecture 11: Signal Separation

- Sound Mixture Organization
- 2 Computational Auditory Scene Analysis
- **3** Independent Component Analysis
- 4 Model-Based Separation

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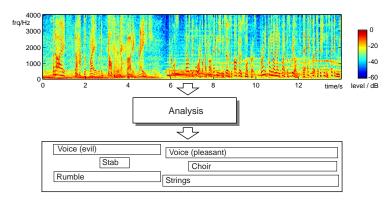
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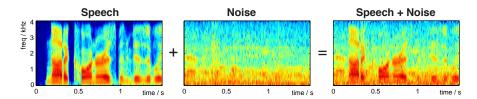
Sound Mixture Organization



- Auditory Scene Analysis: describing a complex sound in terms of high-level sources / events
 - ... like listeners do
- Hearing is ecologically grounded
 - reflects 'natural scene' properties
 - subjective, not absolute



Sound, mixtures, and learning



Sound

- carries useful information about the world
- complements vision

Mixtures

- .. are the rule, not the exception
- medium is 'transparent', sources are many
- must be handled!

Learning

- the 'speech recognition' lesson: let the data do the work
- like listeners

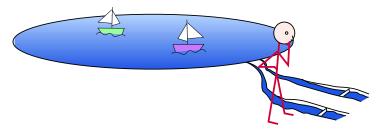
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The problem with recognizing mixtures



"Imagine two narrow channels dug up from the edge of a lake, with handkerchiefs stretched across each one. Looking only at the motion of the handkerchiefs, you are to answer questions such as: How many boats are there on the lake and where are they?" (after Bregman'90)

Received waveform is a mixture

- two sensors, N signals ... underconstrained

Disentangling mixtures as the primary goal?

- perfect solution is not possible
- need experience-based constraints

Approaches to sound mixture recognition

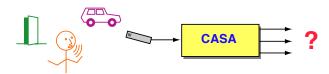
- Separate signals, then recognize
 - e.g. Computational Auditory Scene Analysis (CASA), Independent Component Analysis (ICA)
 - nice, if you can do it
- Recognize combined signal
 - 'multicondition training'
 - combinatorics..
- Recognize with parallel models
 - full joint-state space?
 - divide signal into fragments, then use missing-data recognition

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What is the goal of CASA?



- · Separate signals?
 - output is unmixed waveforms
 - underconstrained, very hard ...
 - too hard? not required?
- Source classification?
 - output is set of event-names
 - listeners do more than this...
- Something in-between?
 Identify independent sources + characteristics
 - standard task, results?



Segregation vs. Inference

- Source separation requires attribute separation
 - sources are characterized by attributes (pitch, loudness, timbre + finer details)
 - need to identify & gather different attributes for different sources ...
- Need representation that segregates attributes
 - spectral decomposition
 - periodicity decomposition
- · Sometimes values can't be separated
 - e.g. unvoiced speech
 - maybe infer factors from probabilistic model?

$$p(O, x, y) \rightarrow p(x, y|O)$$

 or: just skip those values, infer from higher-level context

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Outline

- 1 Sound Mixture Organization
- Computational Auditory Scene Analysis
 - Human Auditory Scene Analysis
 - Bottom-up and Top-down models
 - Evaluation
- 3 Independent Component Analysis
- 4 Model-Based Separation

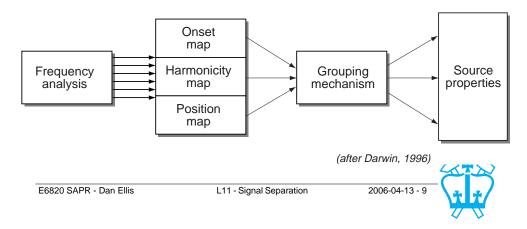




Auditory Scene Analysis

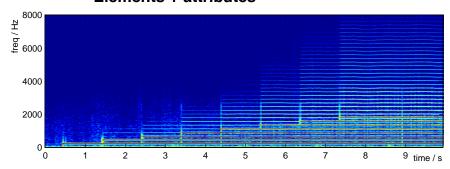
(Bregman 1990)

- How do people analyze sound mixtures?
 - break mixture into small elements (in time-freq)
 - elements are grouped in to sources using cues
 - sources have aggregate attributes
- Grouping 'rules' (Darwin, Carlyon, ...):
 - cues: common onset/offset/modulation, harmonicity, spatial location, ...



Cues to simultaneous grouping

Elements + attributes



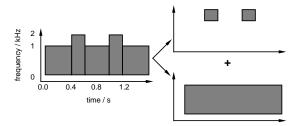
- Common onset
 - simultaneous energy has common source
- Periodicity
 - energy in different bands with same cycle
- Other cues
 - spatial (ITD/IID), familiarity, ...



The effect of context

- Context can create an 'expectation':
 i.e. a bias towards a particular interpretation
- · e.g. Bregman's "old-plus-new" principle:

A change in a signal will be interpreted as an *added* source whenever possible



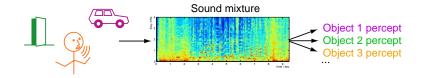
 a different division of the same energy depending on what preceded it

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Computational Auditory Scene Analysis (CASA)



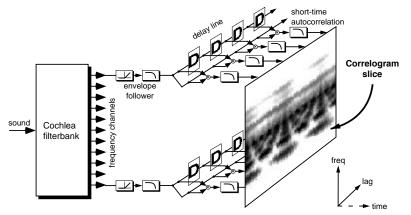
- Goal: Automatic sound organization;
 Systems to 'pick out' sounds in a mixture
 - ... like people do
- E.g. voice against a noisy background
 - to improve speech recognition
- · Approach:
 - psychoacoustics describes grouping 'rules'
 - ... just implement them?



CASA front-end processing

Correlogram:

Loosely based on known/possible physiology



- linear filterbank cochlear approximation
- static nonlinearity
- zero-delay slice is like spectrogram
- periodicity from delay-and-multiply detectors

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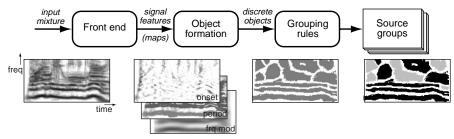
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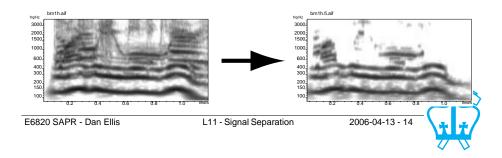
The Representational Approach

(Brown & Cooke 1993)

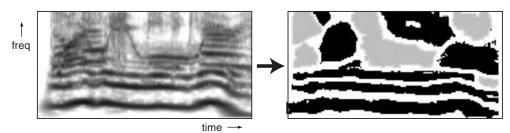
Implement psychoacoustic theory



- 'bottom-up' processing
- uses common onset & periodicity cues
- Able to extract voiced speech:



Problems with 'bottom-up' CASA



- · Circumscribing time-frequency elements
 - need to have 'regions', but hard to find
- Periodicity is the primary cue
 - how to handle aperiodic energy?
- Resynthesis via masked filtering
 - cannot separate within a single t-f element
- Bottom-up leaves no ambiguity or context
 - how to model illusions?

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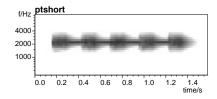
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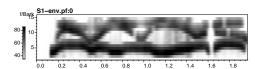


Restoration in sound perception

- Auditory 'illusions' = hearing what's not there
- The continuity illusion



Sinewave Speech (SWS)



- duplex perception
- What kind of model accounts for this?
 - is it an important part of hearing?



Adding top-down constraints: Prediction-Driven CASA (PDCASA)

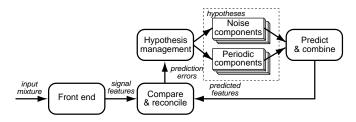
Perception is not direct but a search for plausible hypotheses

Data-driven (bottom-up)...



- objects irresistibly appear

vs. Prediction-driven (top-down)



- match observations with a 'world-model'
- need world-model constraints...

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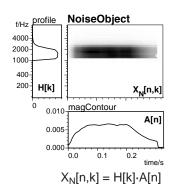
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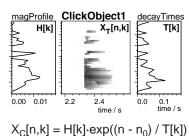
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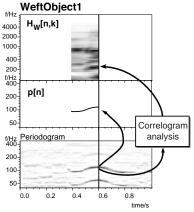


Generic sound elements for PDCASA

- Goal is a representational space that
 - covers real-world perceptual sounds
 - minimal parameterization (sparseness)
 - separate attributes in separate parameters







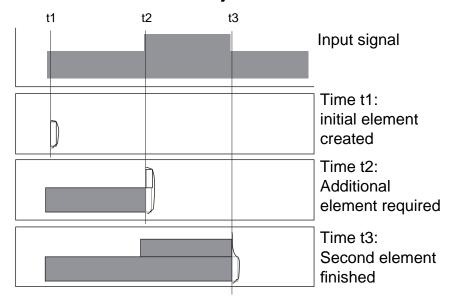
 $X_W[n,k] = H_W[n,k] \cdot P[n,k]$

Object hierarchies built on top...



PDCASA for old-plus-new

Incremental analysis



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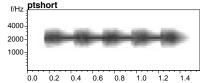
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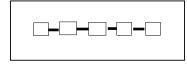
PDCASA for the continuity illusion

Subjects hear the tone as continuous

... if the noise is a plausible masker



• Data-driven analysis gives just visible portions:



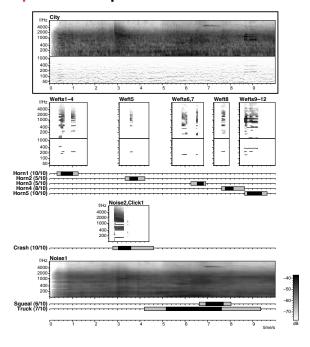
Prediction-driven can infer masking:





Prediction-Driven CASA

Explain a complex sound with basic elements



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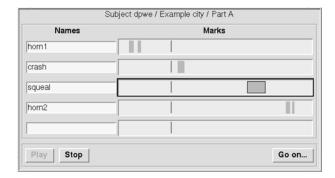
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Aside: Ground Truth

- What do people hear in sound mixtures?
 - do interpretations match?
- → Listening tests to collect 'perceived events':





Aside: Evaluation

- Evaluation is a big problem for CASA
 - what is the goal, really?
 - what is a good test domain?
 - how do you measure performance?
- SNR improvement
 - tricky to derive from before/after signals: correspondence problem
 - can do with fixed filtering mask;
 but rewards removing signal as well as noise
- Speech Recognition (ASR) improvement
 - recognizers typically very sensitive to artefacts
- 'Real' task?
 - mixture corpus with specific sound events...

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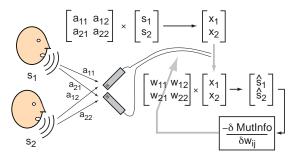
- 1 Sound Mixture Organization
- 2 Computational Auditory Scene Analysis
- **3** Independent Component Analysis
 - Blind source separation
 - Independence and kurtosis
 - Limits of the approach
- 4 Model-Based Separation



3 Independent Component Analysis (ICA)

(Bell & Sejnowski 1995 etc.)

 If mixing is like matrix multiplication, then separation is searching for the inverse matrix



- i.e. W $\approx A^{-1}$
- with N different versions of the mixed signals (microphones), we can find N different input contributions (sources)
- how to rate quality of outputs?i.e. when do outputs look separate?

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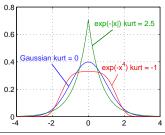
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Gaussianity, Kurtosis & Independence

- A signal can be characterized by its PDF p(x)
 - i.e. as if successive time values are drawn from a random variable (RV)
 - Gaussian PDF is 'least interesting'
 - Sums of independent RVs (PDFs convolved) tend to Gaussian PDF (Weak law of large nums)
- Measures of deviations from Gaussianity:
 4th moment is Kurtosis ("bulging")

$$kurt(y) = E\left[\left(\frac{y-\mu}{\sigma}\right)^4\right] - 3$$



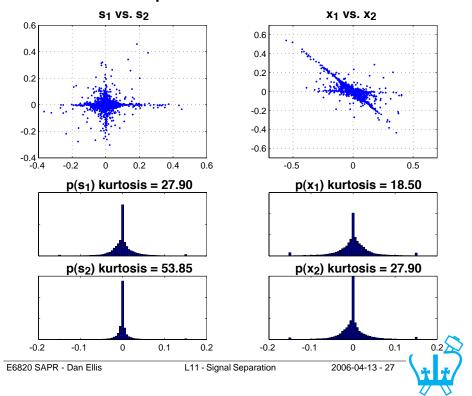
- -kurtosis of Gaussian is zero (this def.)
- -'heavy tails' $\rightarrow kurt > 0$
- -closer to uniform dist. $\rightarrow kurt < 0$
- •Directly related to KL divergence from Gaussian PDF

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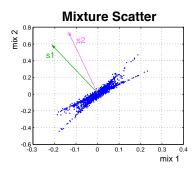
Independence in Mixtures

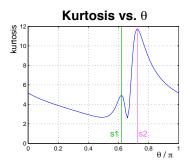
Scatter plots & Kurtosis values



Finding Independent Components

- Sums of independent RVs are more Gaussian
 → minimize Gaussianity to undo sums
 - i.e. search over w_{ij} terms in inverse matrix





Solve by Gradient descent or Newton-Raphson:

$$\mathbf{w}^{+} = E\{\mathbf{x}g(\mathbf{w}^{T}\mathbf{x})\} - E\{g'(\mathbf{w}^{T}\mathbf{x})\}\mathbf{w}$$
$$\mathbf{w} = \mathbf{w}^{+}/||\mathbf{w}^{+}||$$

"Fast ICA", http://www.cis.hut.fi/projects/ica/fastica/ 2

Limitations of ICA

- Assumes instantaneous mixing
 - real world mixtures have delays & reflections
 - STFT domain?

$$x_1(t) = a_{11}(t) \otimes s_1(t) + a_{12}(t) \otimes s_2(t)$$

$$\Rightarrow X_1(\omega) = A_{11}(\omega)S_1(\omega) + A_{12}(\omega)S_2(\omega)$$

Solve ω subbands separately, match up answers

- Searching for best possible inverse matrix
 - cannot find more than N outputs from N inputs but: "projection pursuit" ideas
 time-frequency masking...
- · Cancellation inherently fragile
 - $\hat{s}_1 = w_{11} \cdot x_1 + w_{12} \cdot x_2$ to cancel out s_2
 - sensitive to noise in x channels
 - time-varying mixtures are a problem

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Outline

- Sound Mixture Organization
- 2 Computational Auditory Scene Analysis
- **3** Independent Component Analysis
- 4 Model-Based Separation
 - Fitting models to mixtures
 - Missing-data recognition
 - Speech Fragment Decoding

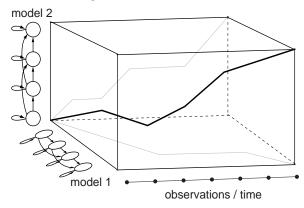




Model-Based Separation: HMM decomposition

(e.g. Varga & Moore 1991, Gales & Young 1996)

Independent state sequences for 2+ component source models



- New combined state space $q' = \{q_1 q_2\}$
 - need pdfs for combinations $p(\boldsymbol{X}|\boldsymbol{q}_1,\boldsymbol{q}_2)$

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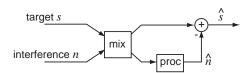
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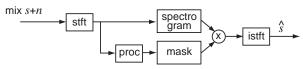


One-channel Separation: Masked Filtering

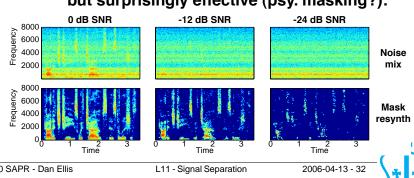
Multichannel → ICA: Inverse filter & cancel



One channel: find a time-frequency mask



Cannot remove overlapping noise in TF cells, but surprisingly effective (psy. masking?):

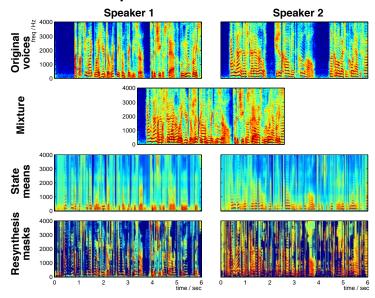


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"One microphone source separation"

(Roweis 2000, Manuel Reyes)

State sequences → t-f estimates → mask



- 1000 states/model (→ 10⁶ transition probs.)
- simplify by subbands (coupled HMM)?

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Speech Fragment Recognition

(Jon Barker & Martin Cooke, Sheffield)

- Signal separation is too hard! Instead:
 - segregate features into partially-observed sources
 - then classify
- Made possible by missing data recognition
 - integrate over uncertainty in observations for true posterior distribution
- Goal: Relate clean speech models P(X|M) to speech-plus-noise mixture observations
 - .. and make it tractable

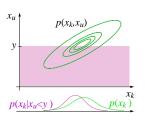


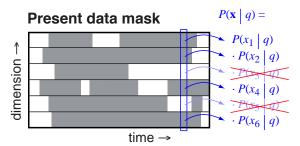
Missing Data Recognition

- Speech models $p(\mathbf{x}|m)$ are multidimensional...
 - i.e. means, variances for every freq. channel
 - need values for all dimensions to get $p(\bullet)$
- But: can evaluate over a subset of dimensions x_k

$$p(\mathbf{x}_k|m) = \int p(\mathbf{x}_k, \mathbf{x}_u|m) d\mathbf{x}_u$$

 Hence, missing data recognition:





- hard part is finding the mask (segregation)

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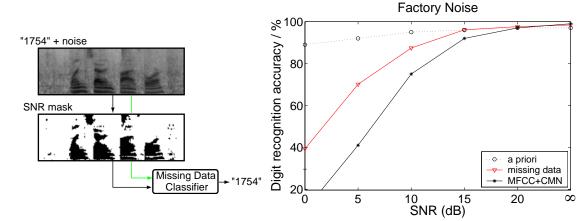
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Missing Data Results

- Estimate static background noise level N(f)
- Cells with energy close to background are considered "missing"



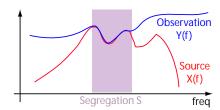
- must use spectral features!
- But: nonstationary noise → spurious mask bits
 - can we try removing parts of mask?

Comparing different segregations

 Standard classification chooses between models M to match source features X

$$M^* = \underset{M}{\operatorname{argmax}} P(M|X) = \underset{M}{\operatorname{argmax}} P(X|M) \cdot \frac{P(M)}{P(X)}$$

• Mixtures: observed features Y, segregation S, all related by P(X|Y,S)



Joint classification of model and segregation:

$$P(M, S|Y) = P(M) \int P(X|M) \cdot \frac{P(X|Y, S)}{P(X)} dX \cdot P(S|Y)$$

- P(X) no longer constant

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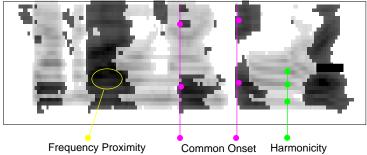
Calculating fragment matches

$$P(M, S|Y) = P(M) \int P(X|M) \cdot \frac{P(X|Y, S)}{P(X)} dX \cdot \frac{P(S|Y)}{P(X)}$$

- P(X|M) the clean-signal feature model
- P(X|Y,S)/P(X) is X 'visible' given segregation?
- Integration collapses some bands...
- P(S|Y) segregation inferred from observation
 - just assume uniform, find S for most likely M
 - or: use extra information in Y to distinguish S's...
- · Result:
 - probabilistically-correct relation between clean-source models P(X|M) and inferred, recognized source + segregation P(M,S|Y)

Using CASA features

- P(S|Y) links acoustic information to segregation
 - is this segregation worth considering?
 - how likely is it?
- Opportunity for CASA-style information to contribute
 - periodicity/harmonicity: these different frequency bands belong together
 - onset/continuity: this time-frequency region must be whole



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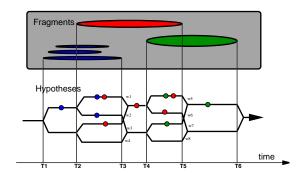
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Fragment decoding

• Limiting *S* to whole fragments makes hypothesis search tractable:

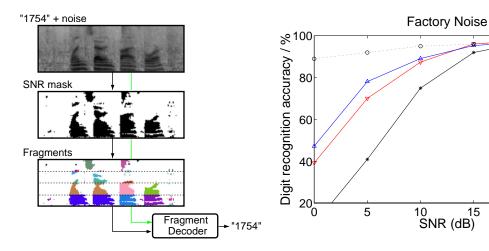


- choice of fragments reflects P(S|Y) · P(X|M)
 i.e. best combination of segregation
 and match to speech models
- Merging hypotheses limits space demands
 - .. but erases specific history



Speech fragment decoder results

- Simple P(S|Y) model forces contiguous regions to stay together
 - big efficiency gain when searching S space



Clean-models-based recognition rivals trained-in-noise recognition

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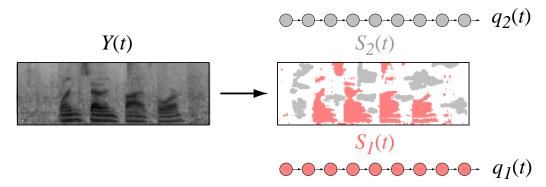
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a priori multisource missing data MFCC+CMN

20

Multi-source decoding

Search for more than one source



- Mutually-dependent data masks
 - disjoint subsets of cells for each source
 - each model match $P(M_x|S_x,Y)$ is independent
 - masks are mutually dependent: $P(S_1, S_2|Y)$
- Huge practical advantage over full search

Summary

- Auditory Scene Analysis:
 Hearing: partially understood, very successful
- Independent Component Analysis:
 Simple and powerful, some practical limits
- Model-based separation:
 Real-world constraints, implementation tricks

Mixture separation the main obstacle in many applications e.g. soundtrack recognition

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