

| | | E 6886 Topics in Signal Processing: Multim | nedia Security Systems |
|-------------------------|---------------------------------|--|------------------------------|
| Course Out | line | | |
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| | | | |
| Multime | dia Security : | | |
| - Mu | timedia Standards – Ubiq | uitous MM | |
| - End | cryption – Confidential MN | | |
| • Wa | termarking – Uninfringible | MM | |
| Aut | hentication – Trustworthy | MM | |
| | | li | |
| | Applications of Multime | eula: ation – Access Control, Identifying | Suspects |
| - Au | veillance Applications – A | hnormality Detection | ouspeets |
| • Me | dia Sensor Networks – Ev | ent Understanding Information Ag | aregation |
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| Inv | isible Waterm | ark |
| Purpose: Protect ownership (Content) Authenti Copy/ Playback co Properties Transmit picture. | and trace illegal use. cation ontrol a bitstream through a very r | noisy channel, i.e. the original |
| Robust: The watern must be able to survi format transformation printing, and scannin Invisible: The water | nark must be very difficult, i ve manipulations to the imag n, shifting, scaling, cropping, g. mark should not visually affe | f not impossible, to remove. It ges, such as: lossy compression, quantization, filtering, xeroxing, ect the image/video content. |
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| С | hou and Li's JND Model |
| | $JND(x,y) = max\{f_1(bg(x,y), mg(x,y)), f_2(bg(x,y))\}$ |
| | where |
| | $f_1(bg(x,y),mg(x,y)) = mg(x,y) \cdot \alpha(bg(x,y)) + \beta(bg(x,y))$ |
| | $f_2(bg(x,y)) = \begin{cases} T_0 \cdot (1 - (bg(x,y)/127)^{0.5}) + 3 & \text{for } bg(x,y) \le 127\\ \gamma \cdot (bg(x,y) - 127) + 3 & \text{for } bg(x,y) > 127 \end{cases}$ |
| | $\alpha(bg(x,y)) = bg(x,y) \cdot 0.0001 + 0.115$ |
| | $eta(bg(x,y)) = \lambda - bg(x,y) \cdot 0.01$ |
| | The experimental result of the parameters are, $T_0 = 17, \ \gamma = \frac{3}{128}$, and $\lambda = \frac{1}{2}$. In this |
| | model, $bg(x,y)$ is the average background luminance, and $mg(x,y)$ is the contrast |
| | value calculated from the output of high-pass filtering at four directions. $f_1 \mbox{ and } f_2$ |
| | model the contrast and luminance masking effects, respectively. |
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| Comparison of Lubin's and Models (II) | Daly's Human Visual System | |
| Amplitude Nonlinea Daly's VDP Local Normalizatie Lubin's VDM N/A | | |
| Subband Decomposi | tion Masking Function Pooling | |
| Daly's VDP Cortex Filters | coherence/learning effect Probability Map | |
| Lubin's VDM Steelable Filters | dipper enect 3ND map | |
| Masking step: In both models, masking functions are applicited filter banks | ied to the intensity of spatial-frequency coefficients obtained by | |
| - Dely uses Wetsen's serter filters which are | a performed in the DET domain | |
| Daiy uses watson's cortex filters, which are | | |
| divide the whole DFT spectrum into 5 circular subbands and each subband is divided into 6 orientation bands. | | |
| boundary of subbands are step functions convolved with Gaussian. In total 31 subbands | | |
| I up uses the steering myramid filters, which are similar to an extended wavelet decomposition | | |
| 7 spatial-frequency decomposition ar In total 28 subbands | nd 4 orientation decomposition. | |
| As for the masking functions: | | |
| Daly uses a function that is controlled by the type of image (noise-like or sine-waves) and the number of learning (the visibility of a fixed change pattern would increase if the viewer observes it for multiple times). | | |
| Lubin uses a function considering the | e dipper effect | |
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| Comparison of Lubin's and Dal | v's Human Visual System |
| Models (III) | |
| | |
| Amplitude Nonlinearity Daly's VDP Local Normalization | Intra-eye blurring Re-sampling CSF N/A N/A SORI |
| Lubin's VDM N/A | optics 120 pxs/deg SQRI |
| Subband Decomposition | Masking Function Pooling |
| Daly's VDP Cortex Filters Lubin's VDM Steerable Filters | coherence/learning effect Probability Map dipper effect JND Map |
| | |
| CSE and masking functions are the | a most important parameters in deciding |
| the masking effect of images | s most important parameters in deciding |
| CSF can be interpreted as a calibra | ation function which is used to normalize the |
| different perceptual importance in dif | ferent spatial-frequency location. |
| Masking funcitons determine how r | nuch change is allowed in each spatial- |
| frequency location based on its value | 25 |
| | |
| | |
| Daly's result – Probability map of v | Isibility |
| Lubin's model – a map of the JND measure is calculated based on the | unit value of each pixel. The distance |
| function (Q is set to 2.4). | Minkowski metile of the output of masking |
| $D = \left(\sum_{i=1}^{m} T_{i} \right)$ | $(10)^{\frac{1}{2}}$ |
| $D_j = \{\sum_{k=1} I_{j,k} \le$ | $I_{1} = I_{j,k}(s_2) ^{s_1} $ |
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| Resources: Papers | | | |
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