

EE 6886: Topics in Signal Processing

-- Multimedia Security System

Lecture 10: Biometric Authentication (III) –Face Recognition

Ching-Yung Lin
Department of Electrical Engineering
Columbia University, New York, NY 10027

Course Outline

▣ Multimedia Security :

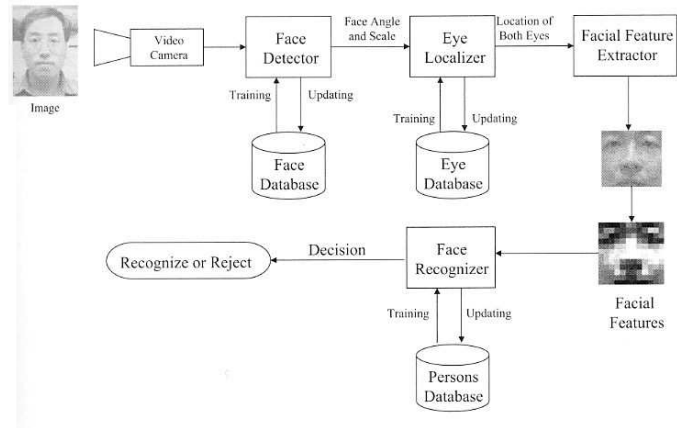
- Multimedia Standards – Ubiquitous MM
- Encryption and Key Management – Confidential MM
- Watermarking – Uninfringible MM
- Authentication – Trustworthy MM

▣ Security Applications of Multimedia:

- Audio-Visual Person Identification – Access Control, Identifying Suspects
- Surveillance Applications – Abnormality Detection
- Media Sensor Networks – Event Understanding, Information Aggregation

Face Recognition -- Introduction

Face Recognition System



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Major Challenges on Face Detection and Recognition

- ❑ Pose: relative camera-face pose (frontal, 45 degree, profile, upside down)
- ❑ Presence or absence of structural components:
 - beards, mustaches, and glasses
 - A great deal of variability among these components
- ❑ Facial expression
- ❑ Occlusion
- ❑ Image orientation
- ❑ Imaging conditions:
 - Lighting (spectra, source distribution and intensity)
 - Camera characteristics (sensor response, lenses)

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Many Aspects on Face Recognition-Related Topics

- ❑ Face localization: determine the image position of a single face, with the assumption that an input image contains only one face.
- ❑ Facial Feature Detection: detect the presence and location of features, such as eyes, nose, nostrils, eyebrow, mouth, lips, ears, etc.
- ❑ Face Identification: compare an input image against a database and reports a match.
- ❑ Face verification (or face authentication): verify the claim of the identity of an individual in an input image.
- ❑ Face tracking: continuously estimate the location and possibly the orientation of a face in an image sequence in real time
- ❑ Facial expression recognition: identify the affective states (happy, sad, disgusted, etc.) of humans.

Categories of Face Detection Algorithms

- ❑ Knowledge-based / Rule-based methods: use known human prior knowledge.
- ❑ Feature invariant approaches: aim to find structural features that exist even when the pose, viewpoint or lighting conditions vary, and then use these to locate faces.
- ❑ Template matching methods: Several standard face patterns are stored to describe the face as a whole or the facial features separately.
- ❑ Appearance-based methods / supervised learning methods: learn models or templates from a set of training images

Categorization of Methods for Face Detection in Image

Categorization of Methods for Face Detection in a Single Image

Approach	Representative Works
Knowledge-based	Multiresolution rule-based method
Feature invariant	
– Facial Features	Grouping of edges
– Texture	Space Gray-Level Dependence matrix (SGLD) of face pattern
– Skin Color	Mixture of Gaussian
– Multiple Features	Integration of skin color, size and shape
Template matching	
– Predefined face templates	Shape template
– Deformable Templates	Active Shape Model (ASM)
Appearance-based method	
– Eigenface	Eigenvector decomposition and clustering
– Distribution-based	Gaussian distribution and multilayer perceptron
– Neural Network	Ensemble of neural networks and arbitration schemes
– Support Vector Machine (SVM)	SVM with polynomial kernel
– Naive Bayes Classifier	Joint statistics of local appearance and position
– Hidden Markov Model (HMM)	Higher order statistics with HMM
– Information-Theoretical Approach	Kullback relative information

Knowledge-based Methods

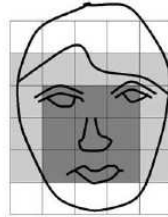
- ❑ Human-specified rules:
 - A face appears in an image with two eyes that are symmetric to each other, a nose, and a mouth.
 - The relations between features can be represented by their relative distances and positions.
 - Facial features in an input image are extracted first, and face candidates are identified based on the coded rules.
 - A verification process is usually applied to reduce false detections.
- ❑ Difficulties of these methods:
 - The trade-off of details and extensibility
 - It is hard to enumerate all possible cases. In a restricted case – heuristics about faces work well in detecting frontal faces in uncluttered scenes.
- ❑ Example: (Yang and Huang 1994) Multiresolution Rule-based Methods
 - Three levels of rules:
 - All possible face candidates are found by scanning a window over the input image.
 - The rules at a higher level are general descriptions of what a face looks like
 - The rules at lower levels rely on details of facial features.



Multiresolution of face image

Knowledge-Based Method – Yang and Huang 1994

- ❑ Rules at the lowest resolution (Level 1):
 - The center part of the face has four cells with a basically uniform intensity
 - The upper round part of a face has a basically uniform intensity
 - The difference between the average gray values of the center part and the upper round part is significant
- ❑ The lowest resolution image is searched for face candidates and these are further processed at finer resolution.
- ❑ Rules at the Level 2:
 - Local histogram equalization is performed on the face candidates regions, followed by edge detection.
- ❑ Rules at the Level 3,
 - Detail rules of eyes and mouth
- ❑ Performance:
 - detect 50 faces out of 60 images.
 - 28 of the detected faces are false alarm
- ❑ Multiresolution approach inspired many follow-up researches.



Knowledge-based Method – Kotropoulos and Pitas 1997

- ❑ Use horizontal and vertical projections of the pixel intensity.
- ❑ The horizontal profile of an input image is obtained first, and then two local minima may correspond to the left and right side of the head.
- ❑ The vertical profile is obtained the the local minima are determined for the locations of mouth lips, nose tip, and eyes.
- ❑ This method has been tested on a video sequence database of 37 different people.
- ❑ Report a detection rate of 86.5%.
- ❑ Have difficulty to locate a face in a complex background.



Feature-based Methods

- ❑ Detect facial features such as eyebrows, eyes, nose, mouth and hair-line based on edge detectors.
- ❑ Based on the extracted features, a statistical model is built to describe their relationships and to verify the existence of face.
- ❑ Features other than facial features:
 - Texture
 - Skin Color
 - Fusion of Multiple Features
- ❑ Difficulties:
 - Face features can be severely corrupted due to illumination, noise and occlusion.
 - Feature boundaries can be weakened for faces, while shadows can cause numerous strong edges which render perceptual grouping algorithm useless.

Feature-based Methods

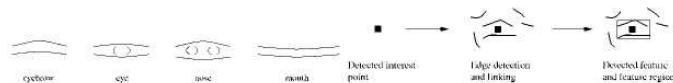
- ❑ Sirohey 1993:
 - Use an edge map (Canny detector) and heuristics to remove and group edges so that only the ones on the face contour are preserved.
 - An ellipse is then fit to the boundary between the head region and the background.
 - Detection accuracy: 80% out of a database of 48 images.
- ❑ Chetverikov and Lerch 1993:
 - Use blobs and streaks (linear sequences of similarly oriented edges).
 - Use two dark blobs and three light blobs to represent eyes, cheekbones and nose.
 - Use streaks to represent the outlines of the faces, eyebrows and lips.
 - Two triangular configurations are utilized to encode the spatial relationship among the blobs.
 - Procedure:
 - A low resolution Laplacian image is generated to facilitate blob detection.
 - The image is scanned to find specific triangular occurrences as candidates
 - A face is detected if streaks are identified around a candidate.

Feature-based Methods

- Graf et. al. 1995:
 - Use bandpass filtering and morphological operations
- Leung et. al. 1995:
 - Use a probabilistic method based on local feature detectors and random graph matching
 - Formulate the face localization problem as a search problem in which the goal is to find the arrangement of certain facial features that is most likely to be a face pattern.
 - Five features (two eyes, two nostrils, and nose/lip junction).
 - For any pair of facial features of the same type, their relative distance is computed and modeled by Gaussian.
 - Report a correct rate of 86%.
 - Use statistical theory of shape (Kendall 1984, Mardia and Dryden 1989), a joint probability density function over N feature points, for the i th feature under the assumption that the original feature points are positioned in the plane according to a general $2N$ -dim Gaussian.

Feature-based Methods

- Yow and Cipolla 1996:
 - The first stage applies a second derivative Gaussian filter, elongated at an aspect ratio of three to one, to a raw image.
 - Interest points, detected at the local maxima in the filter response, indicate the possible locations of facial features.
 - The second stage examines the edges around these interest points and groups them into regions.
 - Measurements of a region's characteristics, such as edge length, edge strength, and intensity variance are computed and stored in a feature vector.
 - Calculate the distance of candidate feature vectors to the training set.
 - This method can detect faces at different orientations and poses.
 - Report a test accuracy of 85%.



Feature-based Methods -- Texture

- ❑ Augusteijn and Skufca 1993:
 - Use second-order statistical features on subimages of 16x16 pixels.
 - Three types of features are considered: skin, hair, and others.
 - Used a cascade correlation neural network for supervised classifications.
- ❑ Dai and Nakano 1996:
 - Use similar method + color
 - The orange-like parts are enhanced.
 - One advantage is that it can detect faces which are not upright or have features such as beards and glasses.
 - Report a detection rate of 100% for a test set of 30 images with 60 faces.

Feature-based Methods – Skin Color

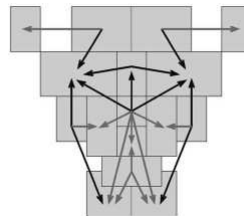
- ❑ Many methods have been proposed to build a skin color model.
- ❑ The simplest model is to define a region of skin tone pixels using Cr and Cb values by carefully chosen thresholds from the training set.
- ❑ Some more complicated models:
 - Histogram intersection
 - Gaussian density functions
 - Gaussian mixture models
- ❑ Color appearance is often unstable due to changes in both background and foreground lighting environments.
- ❑ If the environment is fixed, then skin colors are effective.
- ❑ Several modular systems using a combination of shape analysis, color segmentation and motion information for locating or tracking heads and faces.

Template-based Methods

- ❑ A standard face pattern (usually frontal) is manually predefined or parameterized by a function.
- ❑ Given an input image, the correlation values with the standard patterns are computed for the face contour, eyes, nose and mouth independently.
- ❑ The existence of a face is determined based on the correlation values.
- ❑ Advantage: simple to implement.
- ❑ Disadvantage: need to incorporate other methods to improve the performance

Template-based Methods – Predefined templates

- ❑ Sinha 1994:
 - Designing the invariant based on the relations of regions.
 - While variations in illumination change the individual brightness of different parts of faces remain large unchanged.
 - Determine the pairwise ratios of the brightness of a few such regions and record them as a template.
 - A face is located if an image satisfies all the pairwise brighter-darker constraints.



Appearance-Based Methods

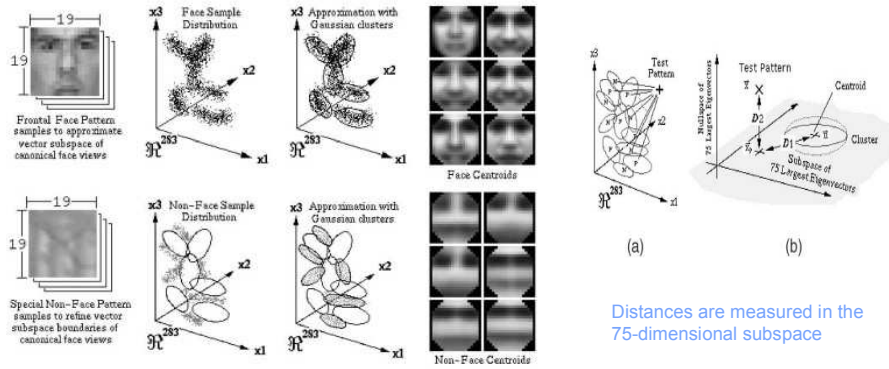
- ❑ Supervised learning
- ❑ Classification of face / non-face
- ❑ Methods:
 - Eigenfaces
 - Distribution-based Methods
 - Neural Networks
 - Support Vector Machines
 - Sparse Network
 - Naïve Bayes Classifier
 - Hidden Markov Model

Appearance-Based Method -- Eigenfaces

- ❑ Apply eigenvectors in face recognition (Kohonen 1989).
 - Use the eigenvectors of the image's autocorrelation matrix.
 - These eigenvectors were later known as Eigenfaces.
- ❑ Images of faces can be linearly encoded using a modest number of basis images.
- ❑ These can be found based on the K-L transform or Principal component analysis (PCA).
- ❑ Try to find out a set of optimal basis vector eigenpictures.
- ❑ Experiments showed that a set of 100 images with face image of 91x50 pixels can be effectively encoded using only 50 eigenpictures.

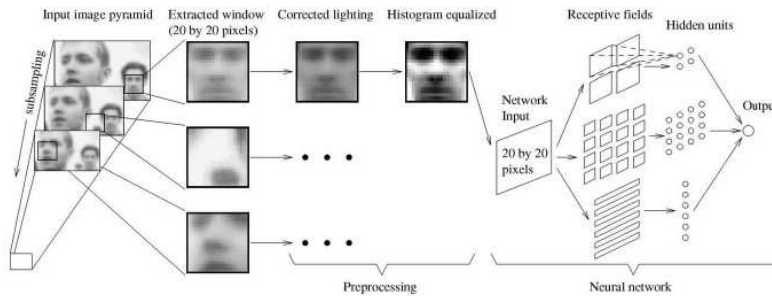
Appearance-based Methods – Distribution-based Methods

- Sung and Poggio 1996:
 - Each face and nonface example is normalized to a 19x19 pixel image and treated as a 361-dimensional vector or pattern.
 - The patterns are grouped into six face and six nonface clusters using a modified k-means algorithm.



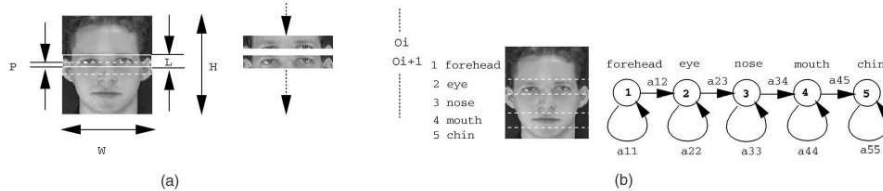
Appearance-based Methods – Neural Network

- Rowley 1996:
 - The first component is a neural network that receives a 20 x 20 pixel region and outputs a score ranging from -1 to 1.
 - Nearly 1050 face samples are used for training.



Appearance-based Method -- HMM

- The goal of training an HMM is to maximize the probability of observing the training data by adjusting the parameters in an HMM model.



Each face sample is converted to a sequence of observation vectors.

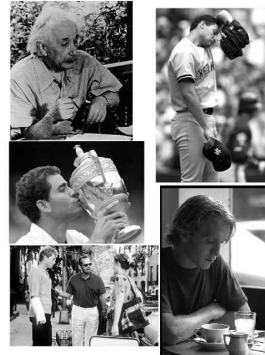
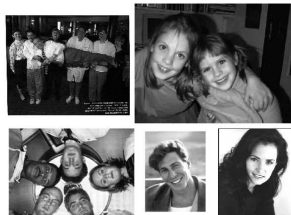
Face Image Database

- These are commonly used face image databases

Data Set	Location	Description
MIT Database [163]	ftp://whitechapel.media.mit.edu/pub/images/	Faces of 16 people, 27 of each person under various illumination conditions, scale and head orientation.
FERET Database [115]	http://www.nist.gov/humanid/feret	A large collection of male and female faces. Each image contains a single person with certain expression.
UMIST Database [56]	http://images.ee.umist.ac.uk/danny/database.html	564 images of 20 subjects. Each subject covers a range of poses from profile to frontal views.
University of Bern Database	ftp://iamftp.unibe.ch/pub/Images/FaceImages/	300 frontal face images of 30 people (10 images per person) and 150 profile face images (5 images per person).
Yale Database [7]	http://cvc.yale.edu	Face images with expressions, glasses under different illumination conditions.
AT&T (Olivetti) Database [136]	http://www.uk.research.att.com	40 subjects, 10 images per subject.
Harvard Database [57]	ftp://ftp.hrl.harvard.edu/pub/faces/	Cropped, masked face images under a wide range of lighting conditions.
M2VTS Database [116]	http://poseidon.csd.auth.gr/M2VTS/index.html	A multimodal database containing various image sequences.
Purdue AR Database [96]	http://rvl1.ecn.purdue.edu/~aleix/aleix_face_DB.html	3,276 face images with different facial expressions and occlusions under different illuminations.

Benchmark for Face Detection

Commonly used test sets



Data Set	Location	Description
MIT Test Set [154]	http://www.cs.cmu.edu/~har	Two sets of high and low resolution gray scale images with multiple faces in complex background.
CMU Test Set [128]	http://www.cs.cmu.edu/~har	130 gray scale images with a total of 507 frontal faces.
CMU Profile Face Test Set [141]	ftp://eyes.ius.cmu.edu/usr20/ftp/testing_face_images.tar.gz	208 gray scale images with faces in profile views.
Kodak Data Set [94]	Eastman Kodak Corporation	Faces of multiple size, pose and under varying illumination in color images. Designed for face detection and recognition.

An experimental results on the performance

A test of several algorithms

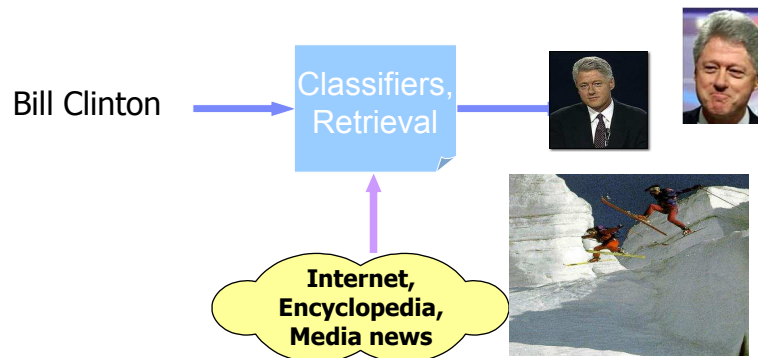
Experimental Results on Images from Test Set 1 (125 Images with 483 Faces) and Test Set 2 (23 Images with 136 Faces) (See Text for Details)

Method	Test Set 1		Test Set 2	
	Detection Rate	False Detections	Detection Rate	False Detections
Distribution based [154]	N/A	N/A	81.9%	13
Neural network [128]	92.5%	862	90.3%	42
Naive Bayes classifier [140]	93.0%	88	91.2%	12
Kullback relative information [24]	98.0%	12758	N/A	N/A
Support vector machine [107]	N/A	N/A	74.2%	20
Mixture of factor analyzers [175]	92.3%	82	89.4%	3
Fisher linear discriminant [175]	93.6%	74	91.5%	1
SNoW with primitive features [176]	94.2%	84	93.6%	3
SNoW with multi-scale features [176]	94.8%	78	94.1%	3
Inductive learning [38]	90%	N/A	N/A	N/A

Face Recognition System

- ❑ Use similar techniques as mentioned in the appearance-based face detection methods.
- ❑ Building personal models based on the training examples.
- ❑ Existing deployed systems:
 - SmartGate at Sydney's airport:
 - Successfully processed 62,000 transactions of 4,200 enrolled Qantas Air crew in a controlled environment.
 - Accuracy > 95%
 - Indetix and Viisage systems at Boston's Logan Airport 2002:
 - Fail to detect suspected criminals 38% of a time.
 - An earlier test at Palm Beach airport fails 53% of the time.

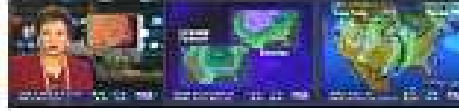
Learning Face Models using Autonomous Learning



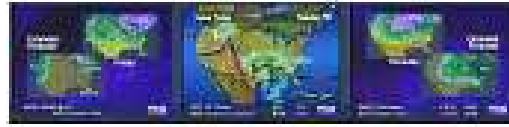
- Automatically build visual models associate with concepts (Bill Clinton, weather news, ...)

Autonomous Learning

- ❑ Correlations between different modalities offers the possibility of autonomous learning
 - Audio, close captions, and visual data in video sequences



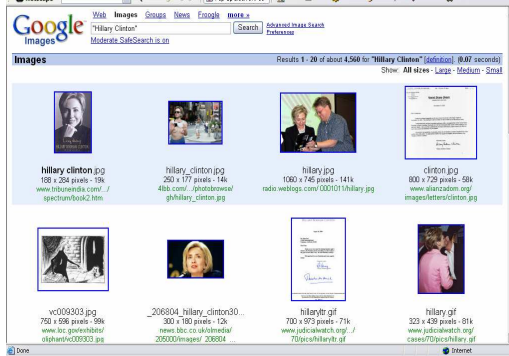
First--let's look at the national weather forecast...
 Unseasonably warm weather expected today in parts of ...



0.7658 0.7682 0.7746

Multi-Modality Correlations

– Texts and images from web images, encyclopedia, ...



Difficulties

- ❑ Uncertainty in the automatic association from the multi-modality data
- ❑ Why we think it may still be feasible?
Consistent cross-modality correlations of the correct association in different occasions



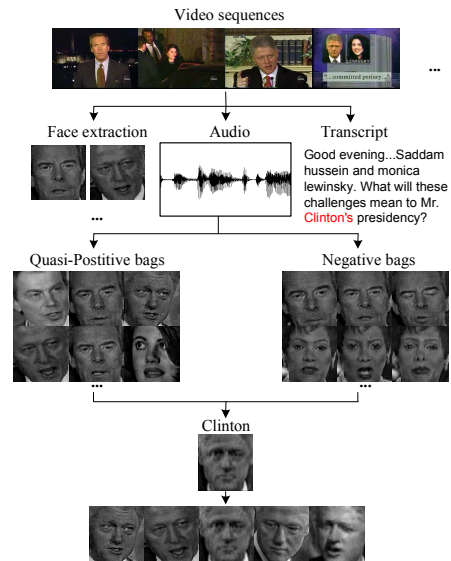
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Learning Face Model from Cross-Modality Information

- ❑ Objective:
 - Generate Visual Concept Models without Annotation
 - Cross-Modality Training using Automatic Speech Recognition Transcription
 - Continuously Learning Concepts from Broadcasting TVs
 - Large Scale of Visual Concept Learning from Sub-Optimal Annotations such as Google Images
- ❑ Methodologies:
 - Multiple Instance Learning with Quasi-Positive Bags
 - Support Vector Machine Regression



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 Example: Training Face Models
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Multiple-Instance Learning

- The trainer only labels **collections** of examples (bags).
- A bag is labeled
 - “negative” if **all** the examples in it are negative.
 - “positive” if there is **at least** one positive example in it.

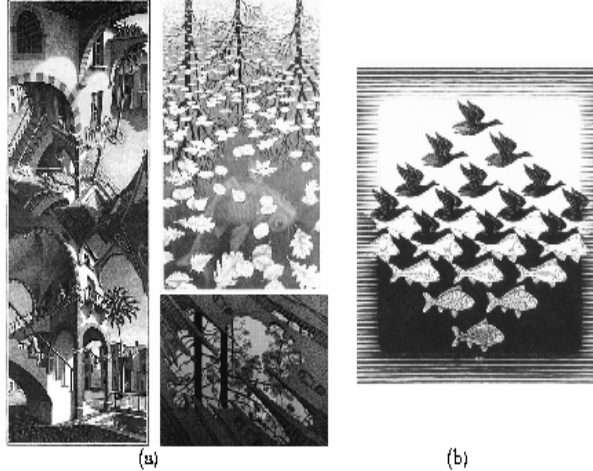


Figure: Some (a) positive and (b) negative training examples

Actual positive instance: Trees [Maron 98]

Diverse Density (DD)

- A method to solve MIL problems
 - Looking for an instance which is close to the instances in **different** positive bags and far from **all** the instances in the negative bags

$$\arg \max_t \prod_i \Pr(t | B_i^+) \prod_j \Pr(t | B_j^-)$$

$$\Pr(t | B_i^+) = 1 - \prod_j (1 - \Pr(t | B_j^+))$$

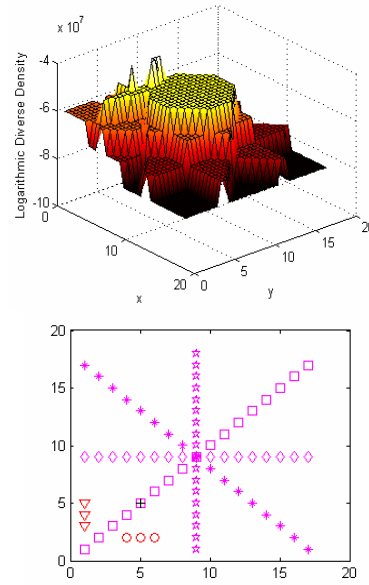
$$\Pr(t | B_j^-) = \prod_j (1 - \Pr(t | B_j^-))$$

$$\text{where } \Pr(t | B_{ij}^+) = \exp\left(-\|B_{ij}^+ - t\|^2\right)$$

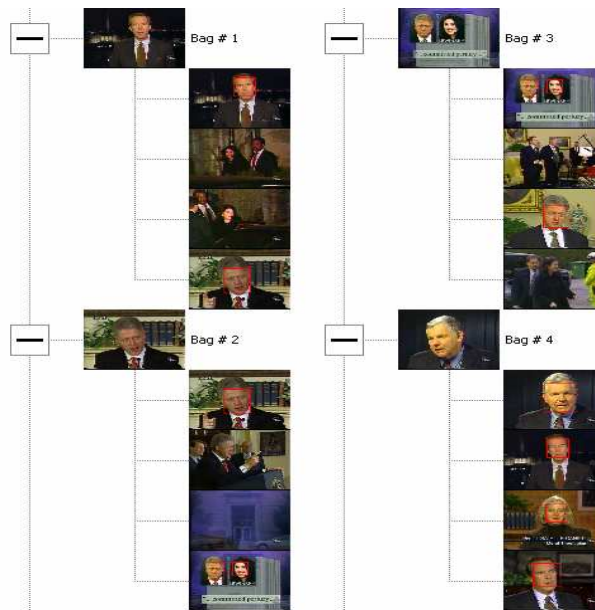
$$\Pr(t | B_{ij}^-) = \exp\left(-\|B_{ij}^- - t\|^2\right)$$

Problem of Diverse Density

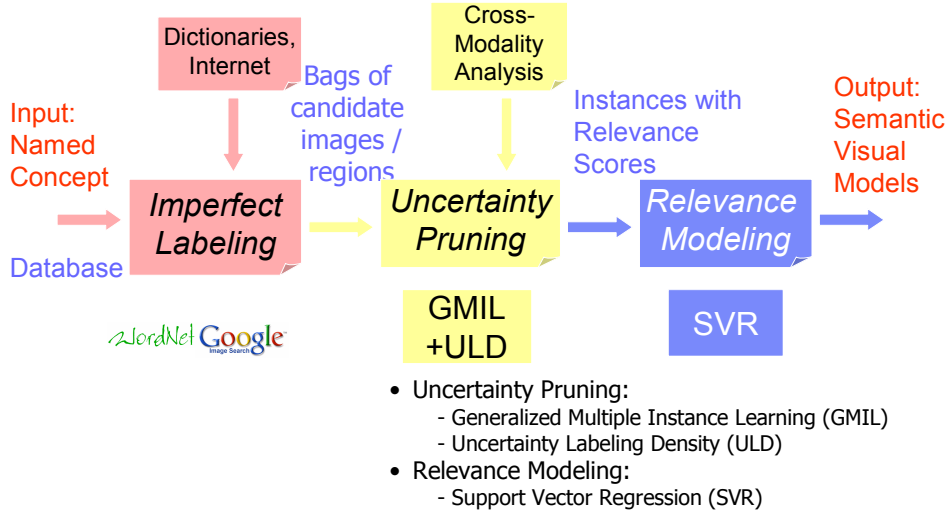
- ❑ With a false-positive bag, $\Pr(t | B_i^+)$ will be very small or even zero.
- ❑ These outliers will influence the result significantly due to the multiplication of the probabilities.



Generalized Multiple Instance Learning



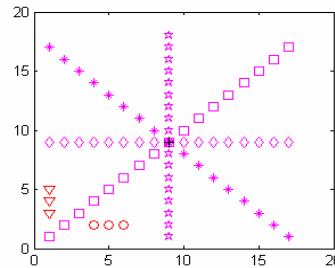
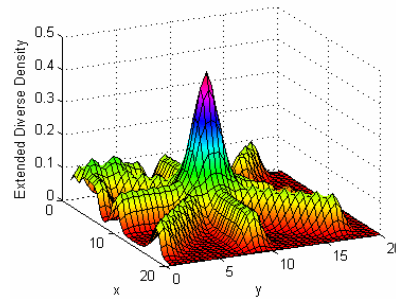
Autonomous Learning Scheme



Uncertain Labeling Density (ULD)

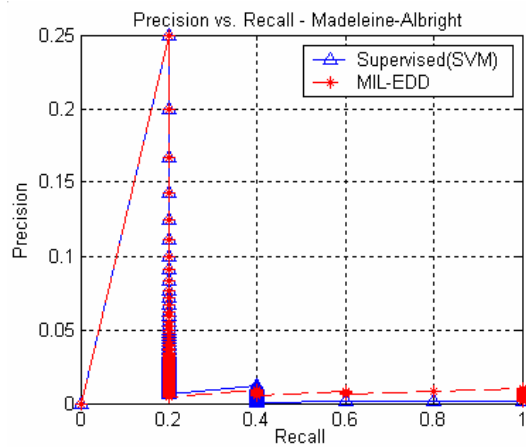
$$\arg \max_i \frac{\sum_i P(t | B_i^+) \cdot \prod_i \Pr(t | B_i^-)}{Z}$$

Z is a normalization constant to keep ULD in [0,1].



Face-Name Association Performance

Baseline: Supervised learning with Support Vector Machine (SVM)

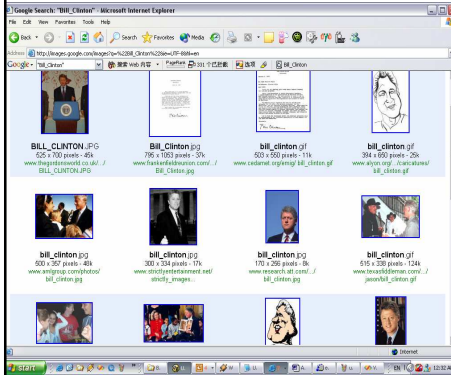


"Albright" Retrieval Rank List

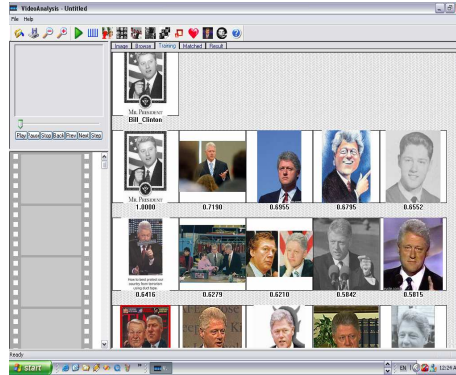


Another Application Example

- Improving Google image search

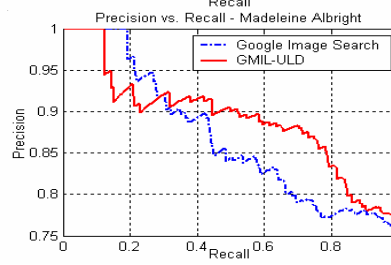
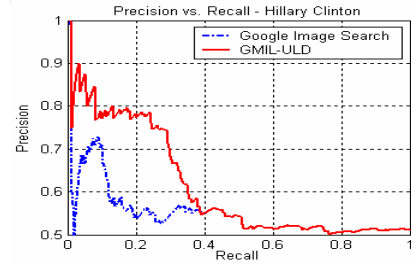
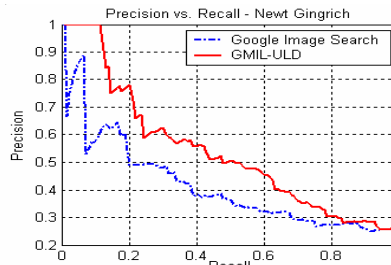
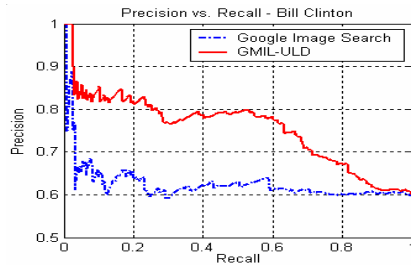


Google image Search
-- Bill Clinton



Improved Google search by cross-modality automatic learning Text & image

Preliminary Detection Results based on Web Annotations



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- ❑ Xiaodan Song, Ching-Yung Lin and Ming-Ting Sun, "**Cross-modality automatic face model training from large video databases**," The First IEEE CVPR Workshop on Face Processing in Video (FPIV'04), June 2004.