

Then, the real-valued matrix T has the following decomposition form: $T = XADBX^\top$. We construct U and V such that $U = XA$ and $V^\top = BX^\top$, which are real and orthogonal. We thus complete the lemma which constructs the SVD of T . \square

Next, we use the following lemma to illustrate that the low rank approximation to a skew-symmetric matrix T generated by singular value thresholding is also skew-symmetric.

Lemma 2. *Let T be an $m \times m$ skew-symmetric matrix, and let $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_j > \lambda_{j+1}$ be the magnitudes of the singular value pairs. (Recall that the previous lemma showed that the singular values come in pairs, e.g., $(i\lambda_p, -i\lambda_p)$, $p = 1, 2, \dots, j$.) Then the low rank approximation of T generated by singular value thresholding in an orthogonally invariant norm is also skew-symmetric.*

Proof. Since the number of singular values of T is even, and there is a gap between the k th and the $(k + 1)$ th singular value, we can always get the even number of singular values if we truncate the singular values based on a threshold. Therefore, based on the SVD form from Lemma 1, we naturally obtain a skew-symmetric matrix. \square

Finally, we use the above lemma to prove that, given a set of n skew-symmetric matrices T_i , our ALM-based algorithm preserves a skew-symmetry matrix $\hat{T}^{(l)}$ in each iteration, where l denotes the iterative number.

Clearly, from Algorithm 1, $\hat{T}^{(0)}$, $E_i^{(0)}$, $Y_i^{(0)}$, $i = 1, \dots, n$ are all skew-symmetric. In step 4 of our algorithm, we compute the SVD of a skew-symmetric matrix $\frac{1}{n\mu} \sum_{i=1}^n Y_i^{(0)} + \frac{1}{n} \sum_{i=1}^n T_i - \frac{1}{n} \sum_{i=1}^n E_i^{(0)}$ and truncate the singular values below the threshold, then the obtained $\hat{T}^{(1)}$ is skew-symmetric based on Lemma 2 and condition of our theorem. In step 5, the obtained $E_i^{(1)}$ is skew-symmetric due to the fact that $T_i + \frac{Y_i^{(0)}}{\mu} - \hat{T}^{(1)}$ is skew-symmetric. Similarly, in step 6, we can obtain $Y_i^{(1)}$ which is also skew-symmetric. As the iteration proceeds, we can obtain skew-symmetric matrices $\hat{T}^{(l)}$, $E_i^{(l)}$, $Y_i^{(l)}$ in each iteration. Therefore, we arrive at a skew-symmetric matrix \hat{T} when Algorithm 1 converges, which completes the proof. \square

References

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