

Homework #2 Solutions

Signals and Systems – Columbia University – Fall 2007

Due 09/20/07

1.1-6

Note:

- Signal Power $P_f = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |f(t)|^2 dt$

$$= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} f(t) \cdot f(t)^* dt$$

= mean squared value of $f(t)$

, where $f(t)^*$ is the complex conjugate of $f(t)$

- rms (root mean-squared value) of $f(t) = \sqrt{P_f}$

- In case of $f(t)$ being a sinusoid, $\lim_{T \rightarrow \infty} \int_{-T/2}^{T/2} |f(t)|^2 dt$ is bound within finite values because of cancellations of the positive and negative areas of a

sinusoid(from Textbook), so if $f(t) = \sum_{n=1}^N C_n \cos(w_n t + \theta_n)$, then, $P_f = \frac{1}{2} \sum_{n=1}^N C_n^2$,

where none of the two sinusoids have identical frequencies.

(c) $f(t) = (10 + 2 \sin 3t) \cos 10t = 10 \cos 10t + 2 \sin 3t \cos 10t$

After using Trigonometric Identities P47

$$= 10 \cos 10t + \sin 13t - \sin 7t,$$

Using the note, we get $P_f = 1/2 * (100 + 1 + 1) = 51$, and $\text{rms} = \sqrt{P_f} = \sqrt{51}$.

(f) $f(t) = e^{i\alpha t} \cos w_0 t$

$$|f(t)|^2 = f(t)f(t)^* = [e^{i\alpha t} \cos w_0 t] \times [e^{-i\alpha t} \cos w_0 t] = \cos^2 w_0 t$$

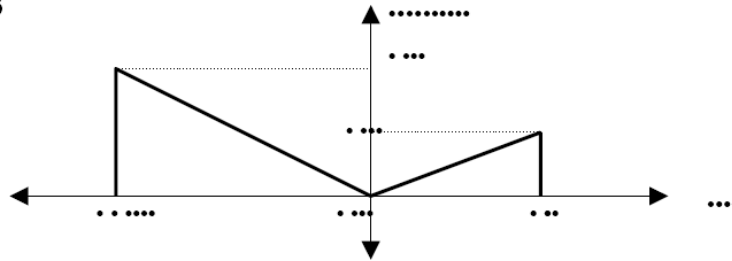
, where $f(t)^* = [e^{i\alpha t} \cos w_0 t]^* = e^{-i\alpha t} \cos w_0 t$

$$= 1/2 * (1 + \cos 2w_0 t), \text{ by using } \sin(x)\cos(y) = (\sin(x-y) + \sin(x+y))/2$$

So, $P_f = (1/4 + 1/4) = 1/2$, and $\text{rms} = \sqrt{P_f} = 1/\sqrt{2}$

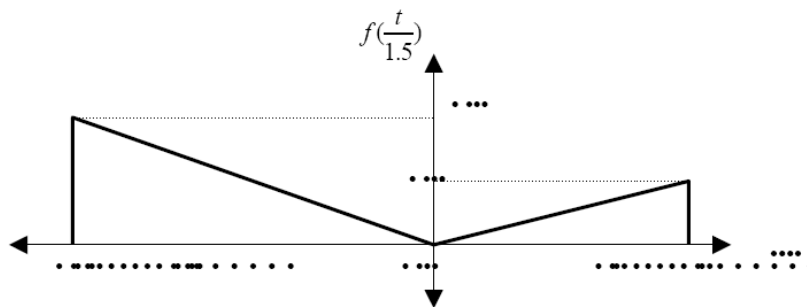
1.3-3

Fig. P1.3-3



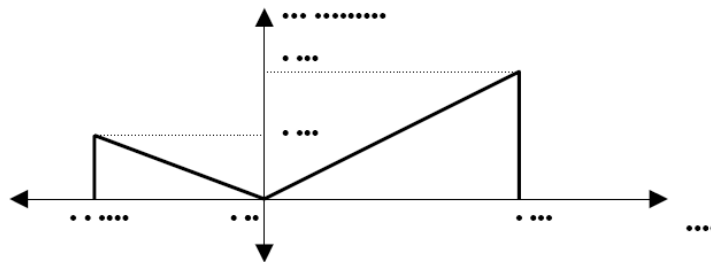
(b) $f\left(\frac{t}{1.5}\right)$

Sol) It's $f(t)$ expanded in time by factor 1.5



(c) $f(-t)$

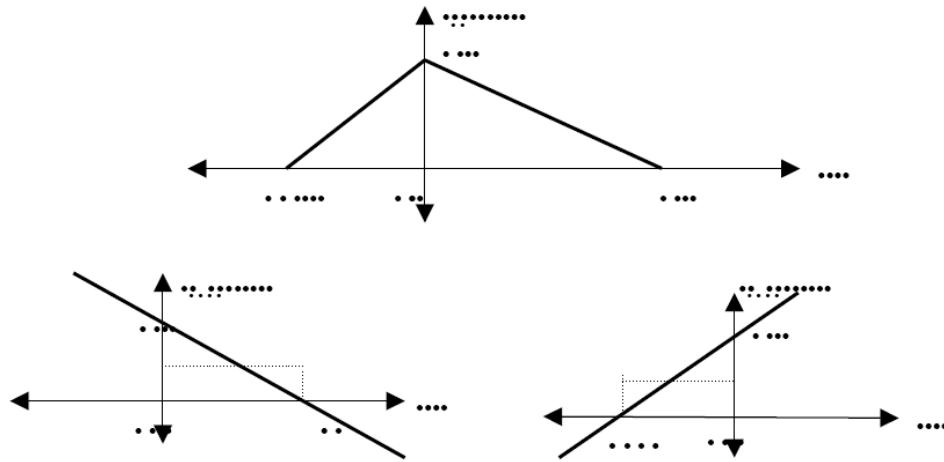
Sol) time invert $f(t)$, which is the mirror image of $f(t)$ about the vertical axis.



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1.4-2

1) Fig P1.4-2 (a)



$$f_1(t) = f_{11}(t) + f_{12}(t)$$

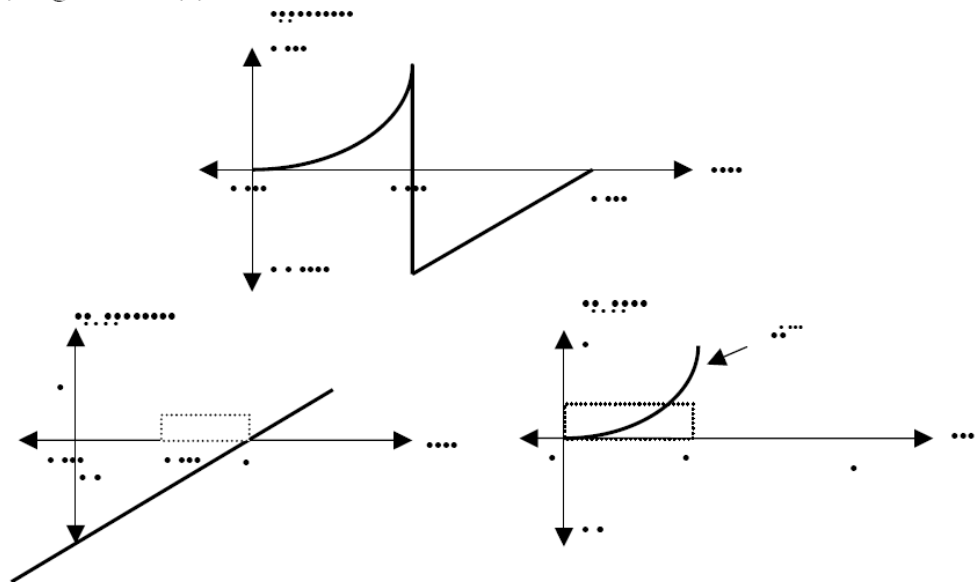
$$\text{where, } f_{11}(t) = (-2t+4)[u(t)-u(t-2)]$$

$$f_{12}(t) = (4t+4)[u(t+1)-u(t)]$$

$$= (-2t+4)[u(t)-u(t-2)] + (4t+4)[u(t+1)-u(t)]$$

$$= (4t+4)u(t+1) - 6tu(t) + (2t-4)u(t-2)$$

2) Fig. P1.4-2 (b)



$$f_2(t) = f_{21}(t) + f_{22}(t)$$

$$\text{where, } f_{21}(t) = (2t-8)[u(t-2)-u(t-4)]$$

$$f_{22}(t) = t^2[u(t)-u(t-2)]$$

$$= (2t-8)[u(t-2)-u(t-4)] + t^2[u(t)-u(t-2)]$$

$$= t^2 u(t) - (t^2 - 2t + 8)u(t-2) - (2t-8)u(t-4)$$

1.4-4

$$(a) \left(\frac{\sin t}{t^2 + 2} \right) \delta(t) = \left(\frac{\sin 0}{0^2 + 2} \right) \delta(t) = 0 \cdot \delta(t) = 0$$

$$(d) \left(\frac{\sin\left[\frac{\pi}{2}(t-2)\right]}{t^2 + 4} \right) \delta(t-1) = \left(\frac{\sin\left[\frac{\pi}{2}(1-2)\right]}{1^2 + 4} \right) \delta(t-1) = -\frac{1}{5} \delta(t-1)$$

1.4-5

$$(b) \int_{-\infty}^{\infty} f(\tau) \delta(t-\tau) d\tau, \text{ which is a function of variable } t.$$

$$\text{,where } \delta(t-\tau) = 0, \text{ at } \tau \neq t, \text{ assuming } -\infty < t < \infty.$$

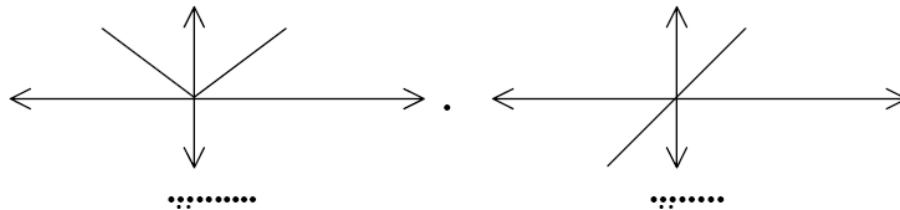
$$\begin{aligned} \text{So, } \int_{-\infty}^{\infty} f(\tau) \delta(t-\tau) d\tau &= \int_{-\infty}^{\infty} f(t) \delta(t-\tau) d\tau \\ &= f(t) \cdot \int_{-\infty}^{\infty} \delta(t-\tau) d\tau \\ &= f(t) \end{aligned}$$

$$\begin{aligned} (e) \int_{-\infty}^{\infty} \delta(t+3) e^{-t} dt &= \int_{-\infty}^{\infty} \delta(t+3) e^3 dt \\ &= e^3 \int_{-\infty}^{\infty} \delta(t+3) dt \\ &= e^3 \end{aligned}$$

1.5-1

$f(t) = f_e(t) + f_o(t)$ where $f_e(t) = 0.5[f(t) + f(-t)]$ and $f_o(t) = 0.5[f(t) - f(-t)]$.

(b) $f_e(t) = 0.5[tu(t) + -tu(-t)] = 0.5[tu(t) - tu(-t)]$
 $f_o(t) = 0.5[tu(t) - -tu(-t)] = 0.5[tu(t) + tu(-t)] = 0.5t$



(d) $f_e(t) = 0.5[\cos(w_0 t)u(t) + \cos(-w_0 t)u(-t)] = 0.5\cos w_0 t$
 $f_o(t) = 0.5[\cos(w_0 t)u(t) - \cos(-w_0 t)u(-t)]$
 $= 0.5[\cos(w_0 t)u(t) - \cos(w_0 t)u(-t)]$
 $= 0.5\cos(w_0 t)[u(t) - u(-t)]$

