

Graph Transduction via Alternating Minimization

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Graph Transduction - A Brief Review

Graph formulation and solution

- Samples (labeled and unlabeled) are treated as graph nodes and pair wise sample similarities are the weights of edges;
- A classification function is learned to propagate labels to unlabeled samples through minimizing a predefined loss function over graph (smoothness evaluation and fitness penalty);

$$\mathbf{F}^* = \arg \min_{\mathbf{F}} \mathcal{Q}(\mathbf{F}) = \arg \min_{\mathbf{F}} \{Q_{smooth}(\mathbf{F}) + Q_{fit}(\mathbf{F})\}$$

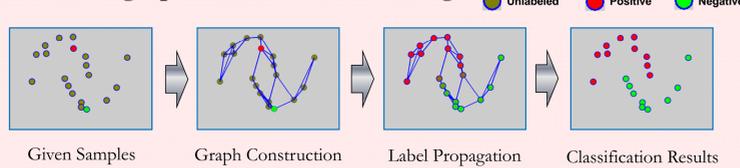
➤ Related work:

Gaussian fields and Harmonic functions *GFHF* (Zhu, Ghahramani, and Lafferty ICML03)
Local and global consistency *LGC* (Zhou, Bousquet, Lal, Weston, and Scholkopf NIPS04)

$$Q(F) = \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n w_{ij} \left\| \frac{F_i}{\sqrt{D_{ii}}} - \frac{F_j}{\sqrt{D_{jj}}} \right\|^2 + \mu \sum_{i=1}^n \|F_i - Y_i\|^2$$

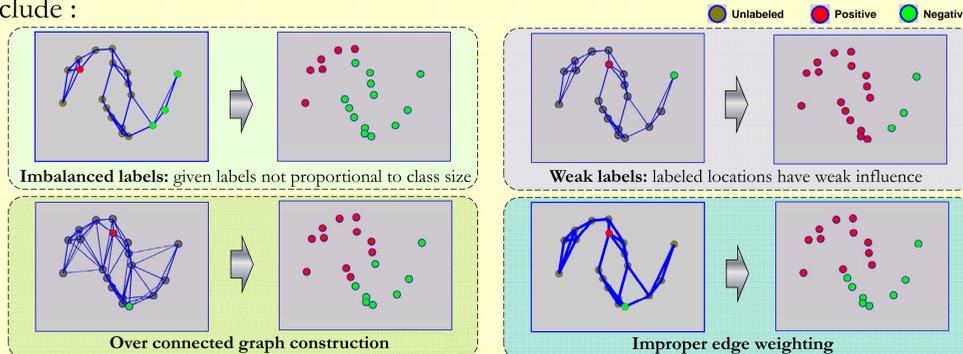
w_{ij} -- weight
 F -- classification function
 Y -- label matrix
 Q -- loss function

Procedure of graph transduction learning



Problem and Motivation

- The derivation of the optimal classification function \mathbf{F} highly relies on the label matrix \mathbf{Y} and is very sensitive to graph construction \mathbf{W} . Several problematic cases include :



- Traditional approaches rely on initial labels which may be imbalanced, noisy, or ill positioned, and try to find optimal \mathbf{F} alone. We propose a new formulation (Graph Transduction via Alternating Minimization *GTAM*) to simultaneously refine the label matrix \mathbf{Y} and find the optimal \mathbf{F} .

New Loss Function

- Revisit the *LGC* formulation: prior work optimizes \mathbf{F} alone

$$Q(\mathbf{F}) = \frac{1}{2} \text{tr} \{ \mathbf{F}^T \mathbf{L} \mathbf{F} + \mu (\mathbf{F} - \mathbf{Y})^T (\mathbf{F} - \mathbf{Y}) \}$$

\mathbf{L} : normalized graph Laplacian

- New formulation: jointly optimizes \mathbf{F} and \mathbf{Y}

$$Q(\mathbf{F}, \mathbf{Y}) = \frac{1}{2} \text{tr} \{ \mathbf{F}^T \mathbf{L} \mathbf{F} + \mu (\mathbf{F} - \mathbf{V} \mathbf{Y})^T (\mathbf{F} - \mathbf{V} \mathbf{Y}) \}$$

$$\mathbf{V} = \sum_{j=1}^c \frac{\mathbf{Y}_j \odot \mathbf{D} \mathbf{I}}{\mathbf{Y}_j^T \mathbf{D} \mathbf{I}}$$

- Additionally, we propose a novel label regularizer with the following two merits.

- Normalizing labels among classes to handle imbalance issue (can incorporate class portion knowledge);
- Weighting labels based on their degree (reduce the impact of unreliable labels);

$$\mathbf{D} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\mathbf{V} = \begin{bmatrix} \frac{1}{1+3} & 0 & 0 & 0 \\ 0 & \frac{2}{2+3} & 0 & 0 \\ 0 & 0 & \frac{3}{3+3} & 0 \\ 0 & 0 & 0 & \frac{4}{4} \end{bmatrix}$$

Greedy Solution by Alternating Minimization

- Optimization on continuous valued \mathbf{F}

$$\frac{\partial Q}{\partial \mathbf{F}^*} = 0 \Rightarrow \mathbf{F}^* = (\mathbf{L}/\mu + \mathbf{I})^{-1} \mathbf{V} \mathbf{Y} = \mathbf{P} \mathbf{V} \mathbf{Y}$$

$$Q(\mathbf{F}^*, \mathbf{Y})$$

$$Q(\mathbf{Y}) = \frac{1}{2} \text{tr} (\mathbf{Y}^T \mathbf{V}^T [\mathbf{P}^T \mathbf{L} \mathbf{P} + \mu (\mathbf{P}^T - \mathbf{I})(\mathbf{P} - \mathbf{I})] \mathbf{V} \mathbf{Y})$$

$$\mathbf{Z} = \mathbf{V} \mathbf{Y} \quad \mathbf{A} = \mathbf{P}^T \mathbf{L} \mathbf{P} + (\mathbf{P}^T - \mathbf{I})(\mathbf{P} - \mathbf{I})$$

- Iterative gradient optimization on discrete valued \mathbf{Y}

$$Q(\mathbf{Z}) = \frac{1}{2} \text{tr} (\mathbf{Z}^T \mathbf{A} \mathbf{Z}) \quad \frac{\partial Q^{(t)}}{\partial \mathbf{Z}} = \mathbf{A} \mathbf{Z}^t = \mathbf{A} \mathbf{V}^t \mathbf{Y}^t$$

set the best label that achieves the largest cost reduction

$$(i^*, j^*) = \arg \min_{\mathbf{x}_i \in \mathcal{X}_u, 1 \leq j \leq c} \nabla_{\mathbf{Z}_{ij}} Q$$

update iteration counter

$$\begin{aligned} \mathcal{X}_u^{t+1} &\leftarrow \mathcal{X}_l^t + \mathbf{x}_{i^*} \\ \mathcal{X}_l^{t+1} &\leftarrow \mathcal{X}_l^t - \mathbf{x}_{i^*} \end{aligned}$$

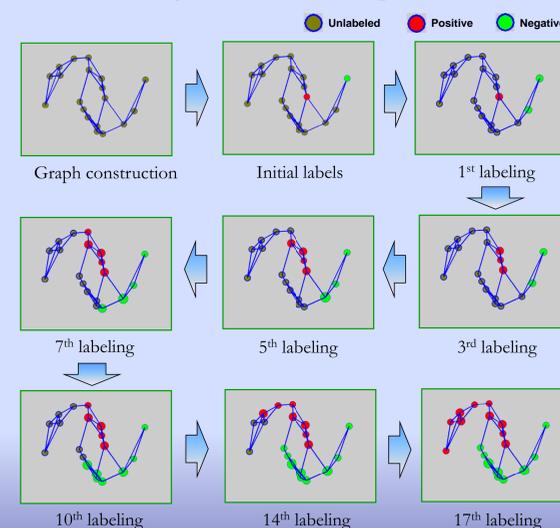
Update labeled and unlabeled sets

$$\mathbf{V}^{t+1} = \sum_{j=1}^c \frac{\mathbf{Y}_j^{t+1} \odot \mathbf{D} \mathbf{I}}{\mathbf{Y}_j^{t+1 T} \mathbf{D} \mathbf{I}}$$

Update label regularizer

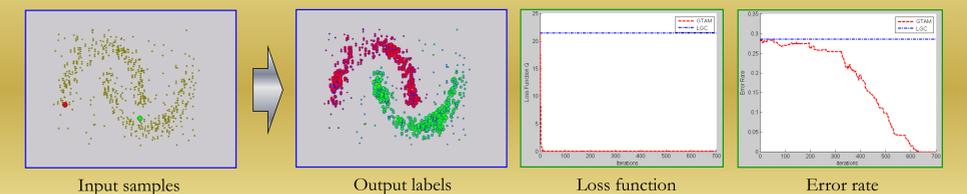
Intuitive Demonstration

- Given a set of labeled samples, *GTAM* chooses the most beneficial data with largest cost reduction over the whole graph for label assignment, one sample in each iteration.

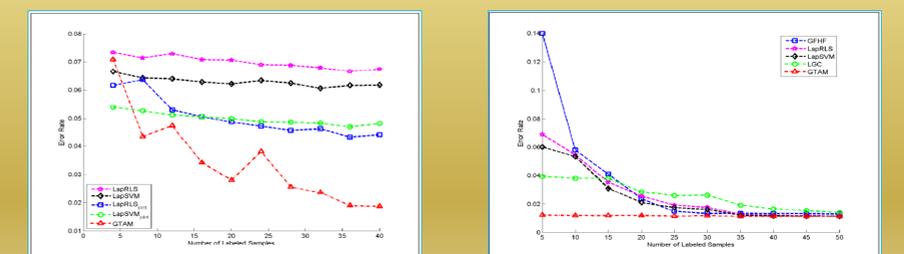


Experiments

- Artificial two – moon noisy data



- Text Classification (WebKB data) ■ Image Classification – USPS digits



Performance comparison on text classification (WebKB dataset). The horizontal axis represents the number of randomly observed labels (guaranteeing there is at least one label for each class). The vertical axis shows the average error rate over 100 random trials.

Performance comparison on image classification (USPS digits). The horizontal axis shows the total number of randomly observed labels (guaranteeing there is at least one label for each class). The vertical axis shows the average error rate over 20 random trials.