

Active Query Sensing for Mobile Location Search

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Outline

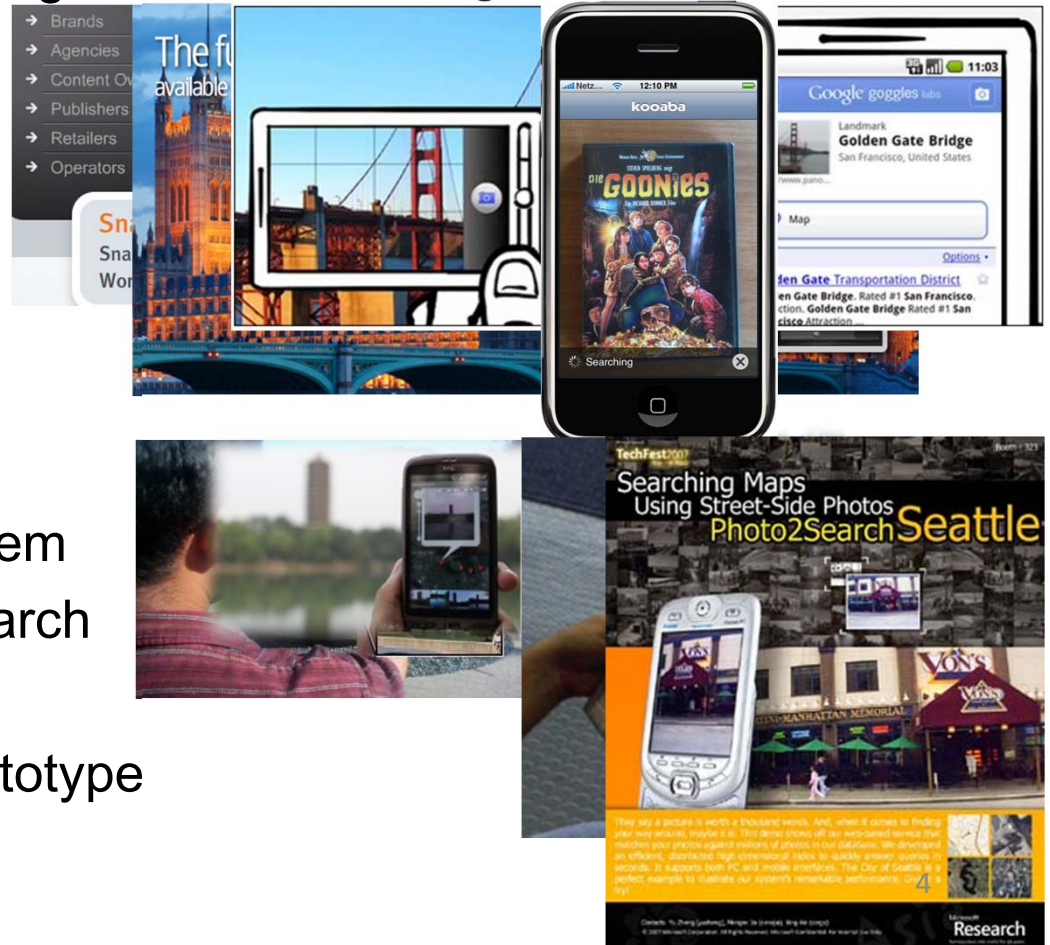
- Motivation
- Problem Justification
- Active Query Sensing
 - Offline Salient View Learning
 - Online Active Query Sensing
- Evaluation
- User Interface
- Conclusion

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Motivation

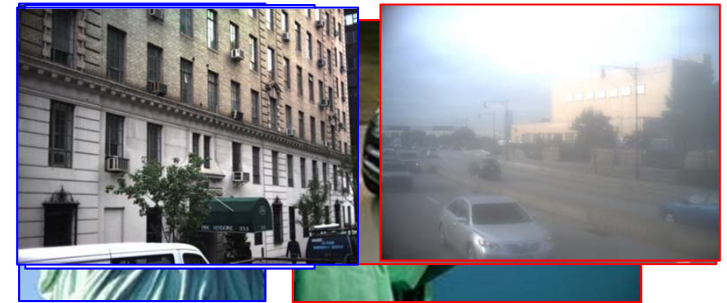
- Mobile Visual Search
 - Search information about products, locations, or landmarks
 - By taking a photo of the target of interest using the mobile device
- Commercial Systems
 - Snaptell
 - Nokia point and find
 - Google goggles
 - Kooaba
- Research Prototypes
 - Nokia Stanford MVS system
 - PKU mobile landmark search
 - MIT sixth senses
 - MSRA Photo2Search prototype



Motivation

Performance of Mobile Visual Search Varies

- Search success depends on
 - How distinctive object classes are
 - View variation and object deformation
 - Quality of captured images
- **Not every view** of an object or location is distinctive enough as a successful query
 - Only 47% of the first query succeed in our location search endeavor on Manhattan 0.3m street view dataset
 - 0.4-0.7 *average precision* in the state-of-the-art location search systems ([Knopp 2010] [Girod 2011] etc.)



Motivation

How to guide the user to take the mobile query?

- Which view will be the best query?
 - For example, in mobile location search:



- Or in mobile product search:



- A General Yet Untouched Problem for searching locations, objects and landmarks.

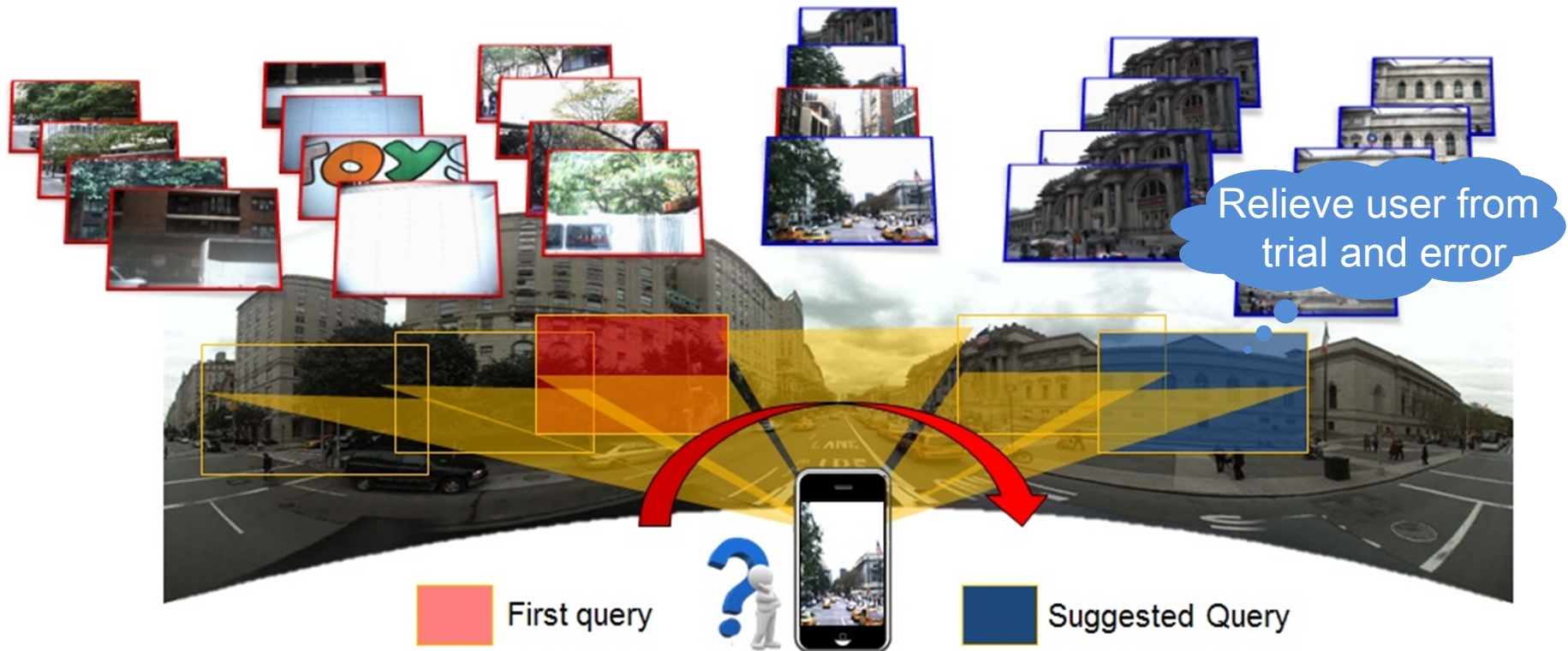
Motivation

- Possible Solutions

- Solution I

- User takes a video query by scanning the surrounding
 - Then the mobile end selects (views) to be sent to the

We focus on solution II, enabling users and machines to collaborate



Motivation

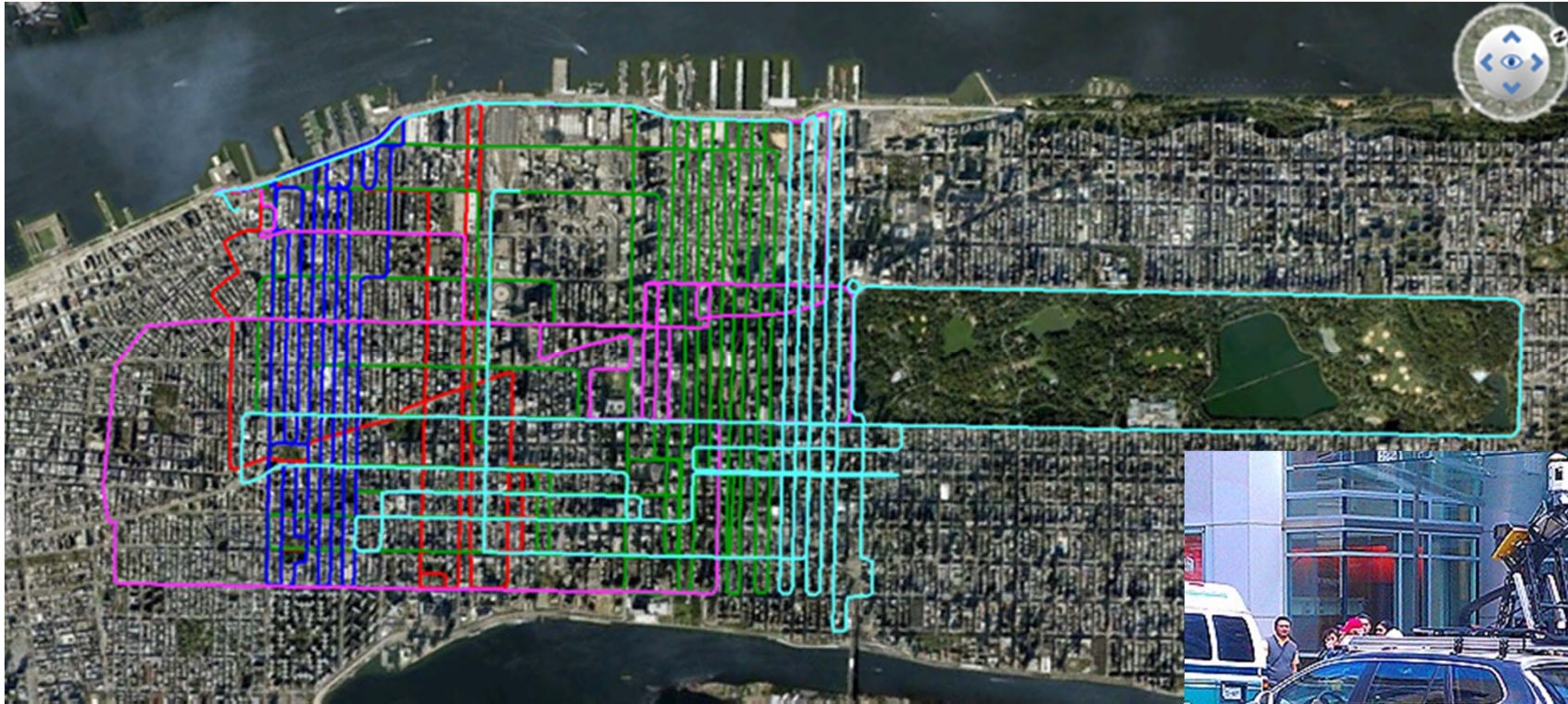
- Research Objective
 - Use **mobile location search** as a case study
 - We will develop a general framework that can be extended to mobile object retrieval and product search
 - **Why not GPS?**
 - GPS may **not be reliable** in the dense urban jungle areas
 - Visual based solutions can also be used to **refine** GPS solutions
 - Our research goal is general: **a special case of multi-view mobile search**

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NAVTEQ 0.3M NYC Data Set

- 300,000 images of 50,000 locations in Manhattan
- Collected by the NAVTEQ street view imaging system

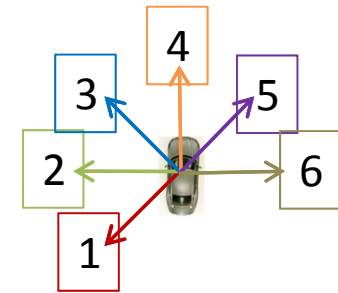


Geographical distribution



NAVTEQ 0.3M NYC Data Set

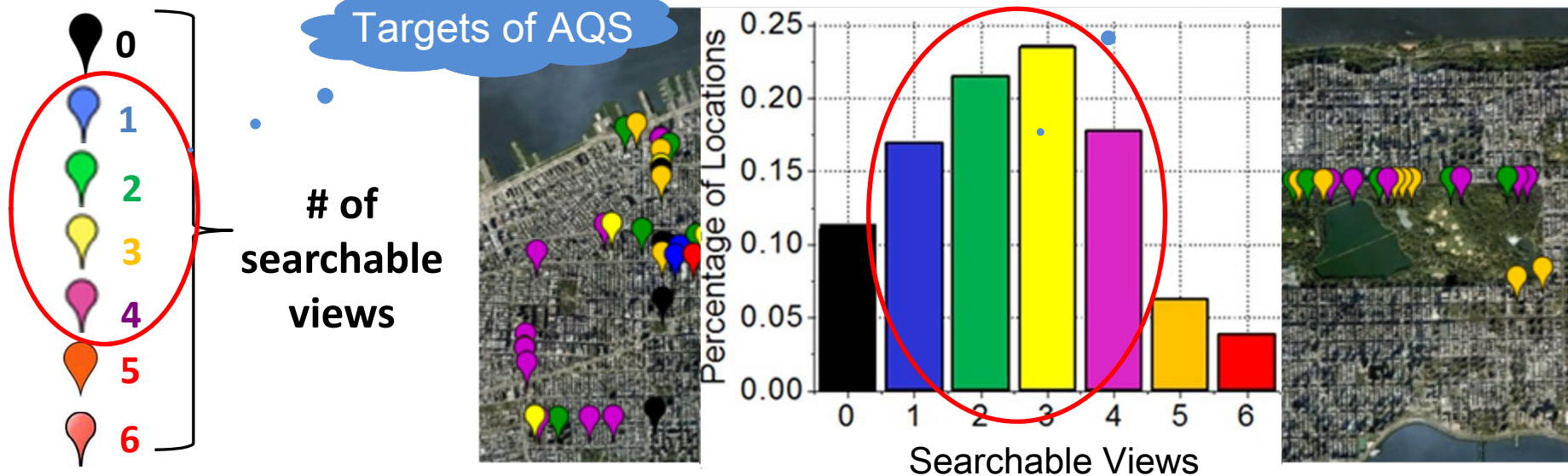
- Location Sampling
 - Locations are imaged at a four-meter interval on average
 - Six camera views for each location separated by 45°
- Visual Data Organization
 - Six views (images)
 - Also provide panorama (used for visualization in this work)



Problem Justification

- Our goal
 - Once the first query fail, how to take the **best second query** to correctly find his/her current correct location
- How much can AQS help
 - The percentage of locations that are partially searchable

80% of locations have partial searchable views



Subsample 200 locations to “# of searchable views” using cropped Google street view

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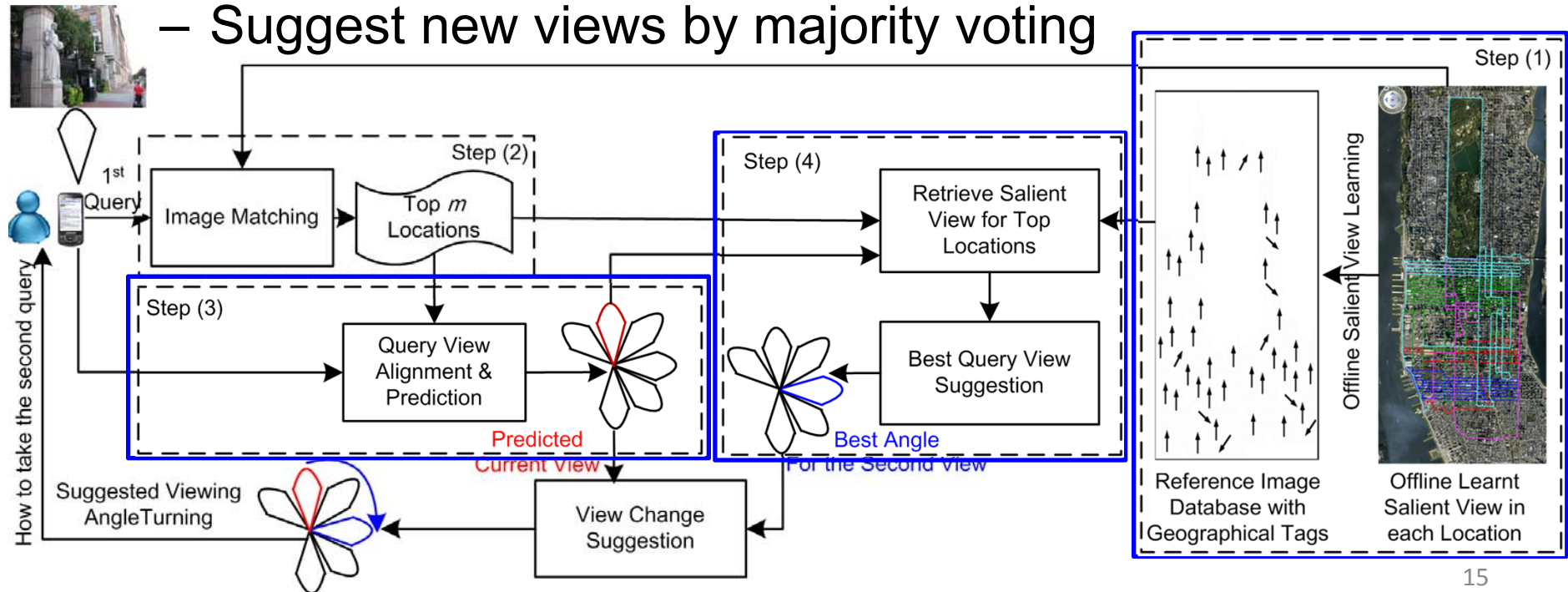
Active Query Sensing System

- Active Query Sensing Demo
(refer the demo video)

Active Query Sensing System

Basic Idea and Workflow

- Offline
 - Salient view learning for each reference location
- Online
 - Viewing angle prediction of the first query
 - Suggest new views by majority voting



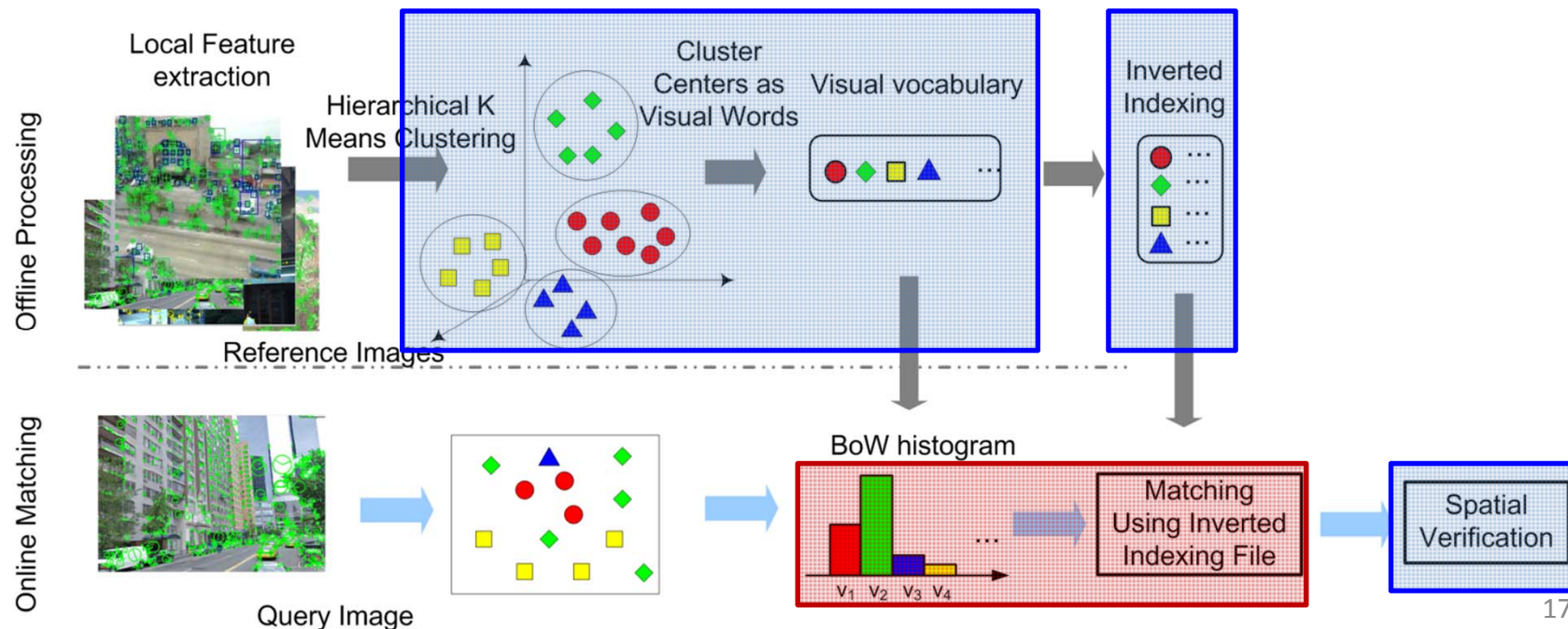
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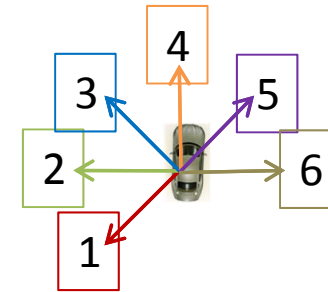
Million Scale Image Matching

Extend and modify from [Nister 06][Schindler 07]

- Offline
 - Codebook construction and BoW quantization
 - Inverted location/image indexing
- Online
 - Inverted indexing based search + spatial verification



Location Score Calculation



Location i

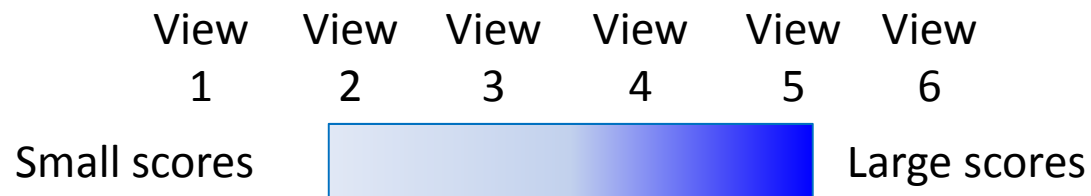
1	2	3	4	5	6
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Location j

1	2	3	4	5	6
---	---	---	---	---	---

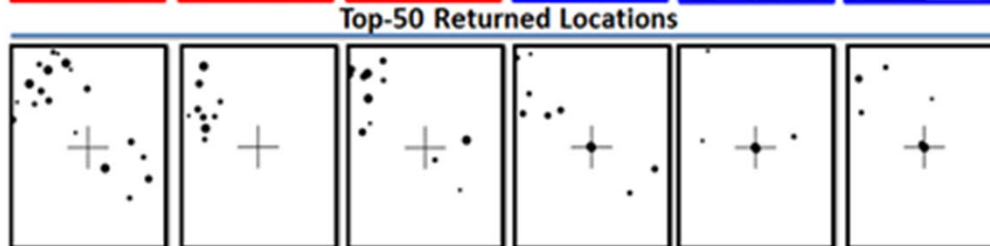
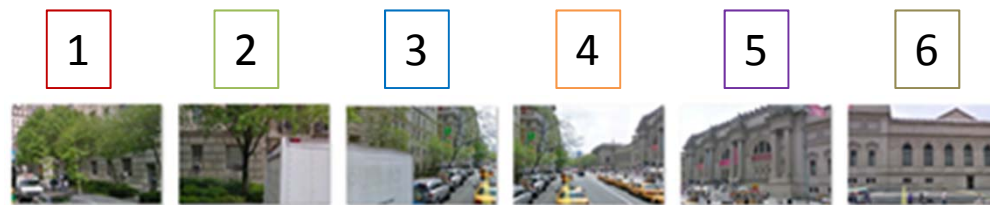
Location k

1	2	3	4	5	6
---	---	---	---	---	---



Offline: Salient View Learning

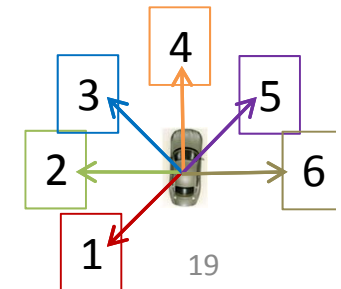
- Question
 - Among 6 views of a location, which is most informative?
- Definition
 - **Salient view** is the most discriminative view in a location



Six Views

Query over the salient view
can lead to successful

Geographical
scatter graph



Offline Salient View Learning

- Solution I: Content-based prediction

- Occurrence of attributes/content

- Such as detecting discriminative objects in this image

- Visual word discriminability distribution

- Step I

- Measure the frequency of the discriminative words

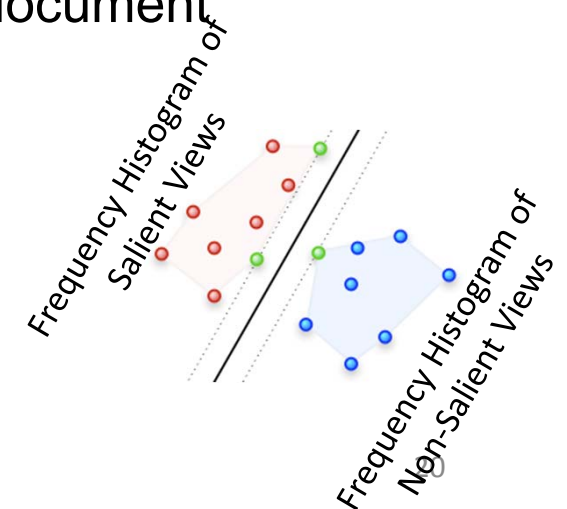
- Use term frequency and inverted document frequency

- Build a TF-IDF frequency histogram

- Example of discriminative words

- Step II

- Train SVM on to predict the saliency

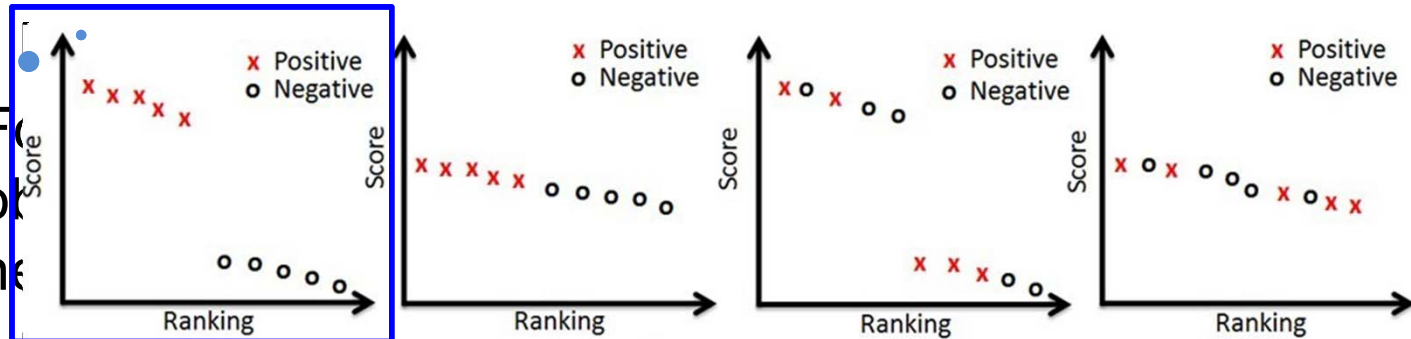


Offline Salient View Learning

- Solution II: Self retrieval testing
 - Goal: Determine whether a view is salient
 - Approach: Using the reference image of each view to retrieve the corresponding location

• Step I

An ideal score distribution



• Step II

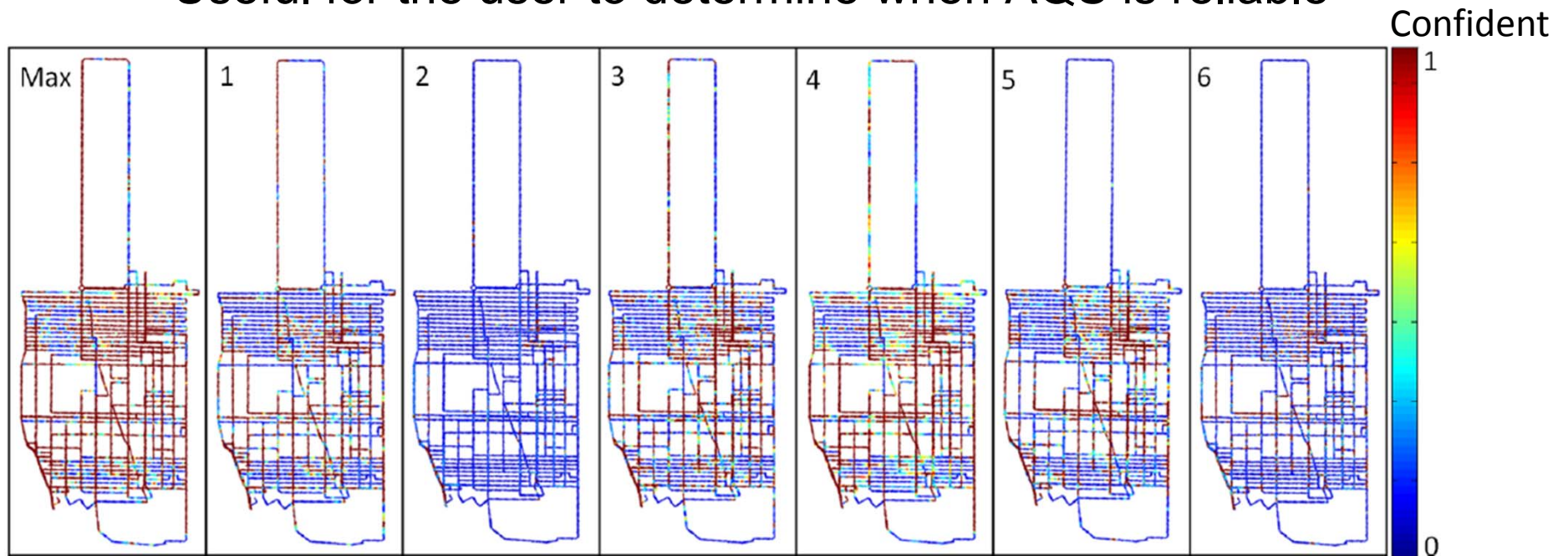
$$Saliency = \frac{\sum_{i=1}^N \sum_{j=1}^i score(j)rel(j)/i}{\sum_{i=1}^N \sum_{j=1}^i score(j)\overline{rel}(j)/i},$$

- (2) (1) N is the number of returned locations. at r .
- (2) $score(j)$ is the location matching score: the maximal score of its six views.
- (3) $rel(j)$ is the relevance judgement of the j th returned location, 1:correct, 0:incorrect.

Saliency Measure

Can be also used to access the location difficulty

- We define the confidence of each location as proportional to its saliency (max of the six views)
- Useful for the user to determine when AQS is reliable



Geographical location confidence distribution

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Online Active Query Sensing

Examples of “junk” images:



Examples of query images selected by user:



- Assumption
 - User is unlikely to take “junk image” with no hope for finding the true target.
 - The first query, even unsuccessful, can be used as “probe” to narrow down the solution space.

Online Active Query Sensing

- Formulation
 - Maximizing uncertainty reduction

$$v_2 = \max_v (H(l|q_1) - H(l|q_1, v))$$

- A subsequent query should
 - maximize the uncertainty reduction (information gain)
 - across candidate locations, narrowed down by the query already been taken
 - in terms of getting the best view

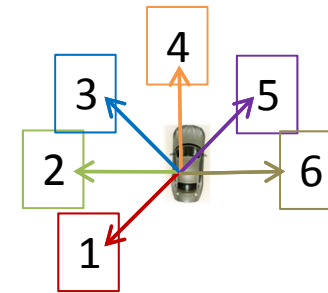
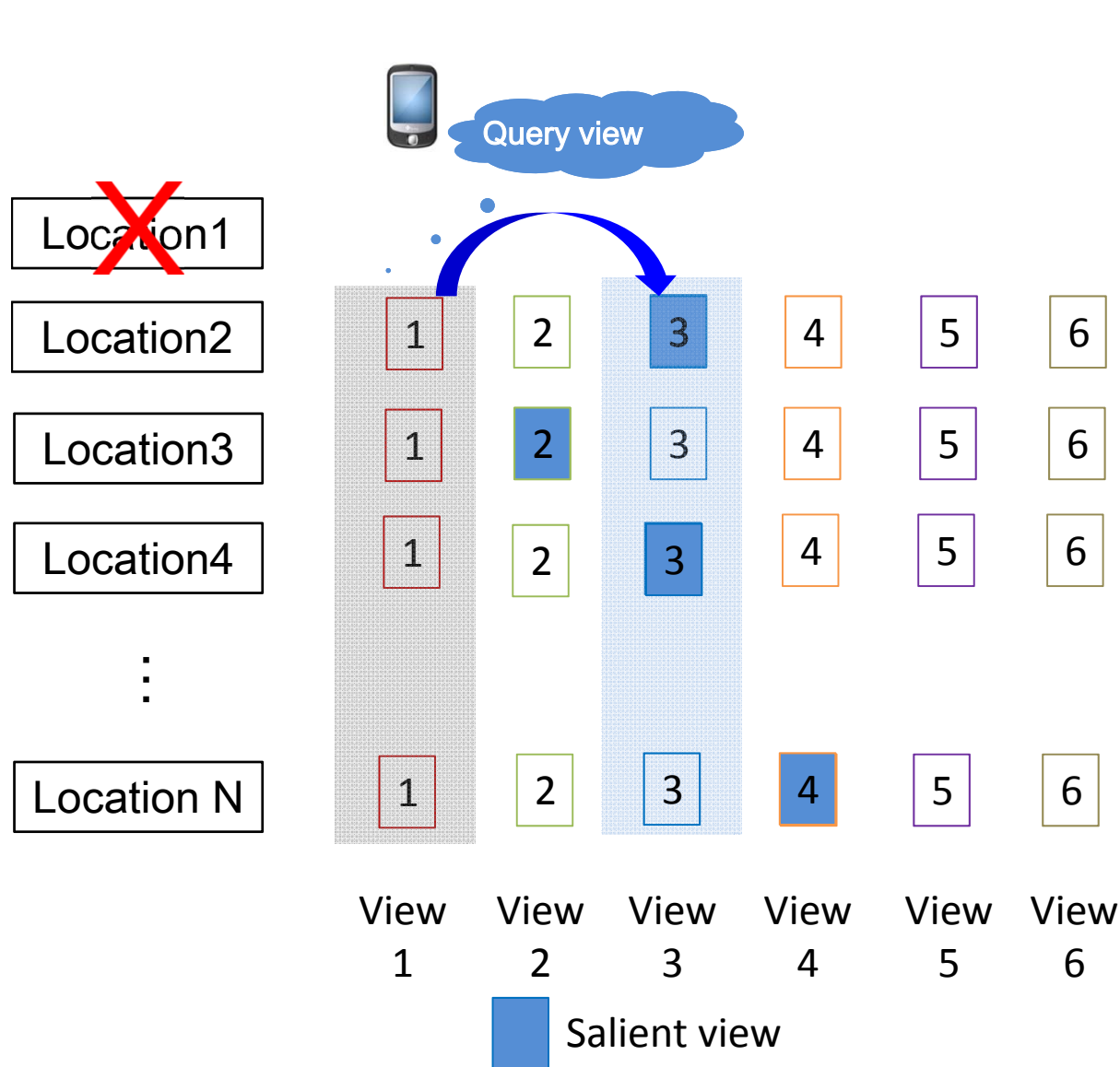
Online Active Query Sensing

- In practice, we find maximizing uncertainty reduction can be well approximated by:

$$\max_v \sum_{l \in L_N} \textit{Saliency}(l, v)$$

- L_N is the candidate locations narrowed down by the first query.
- In other words, AQS suggests the user to turn to the “most salient” view by a weighted sum or majority voting in terms of *Saliency*.

Online Active Query Sensing



For each location, we have its most salient view

The majority of the salient views decides the suggested (second) query

What about current view unknown?

- Step I: Predict the view angle of the first query

Offline Training: Train view prediction classifiers offline



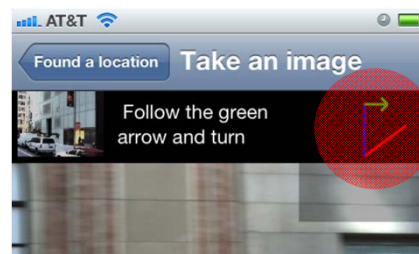
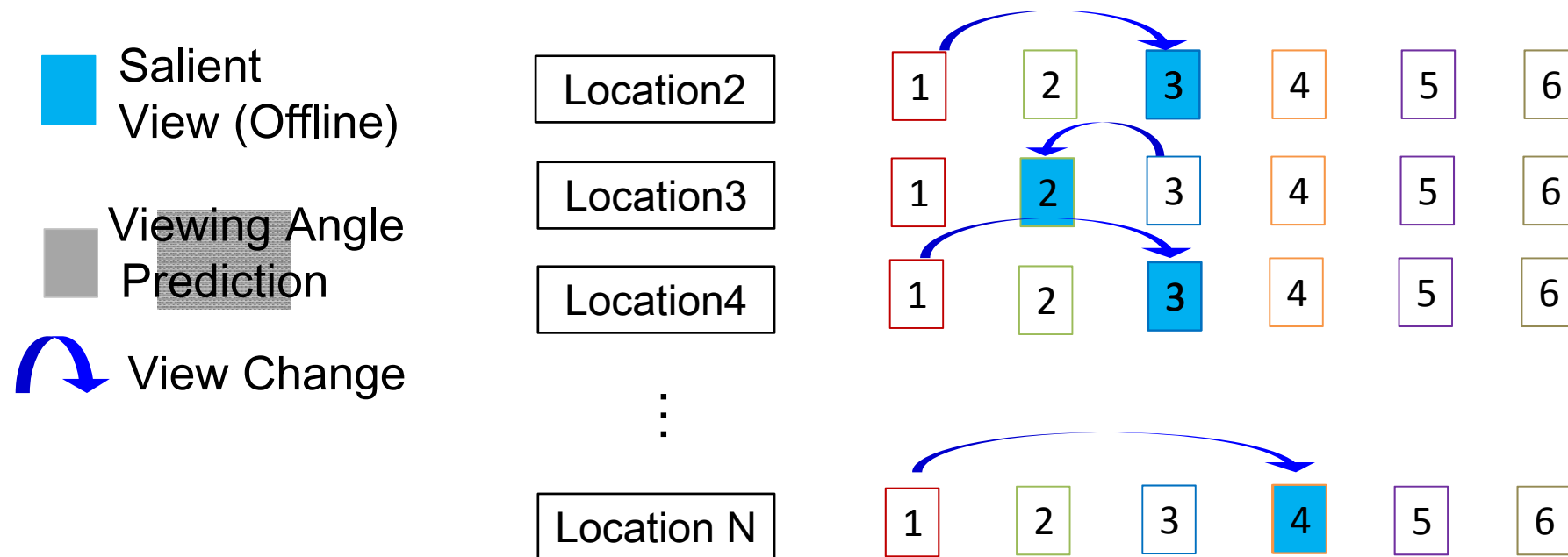
Online Prediction: View alignment based on the image matching



Our solution is to combine them both

What about current view unknown?

- Step II: Majority voting in terms of view change



Turn 90 degrees
to the right

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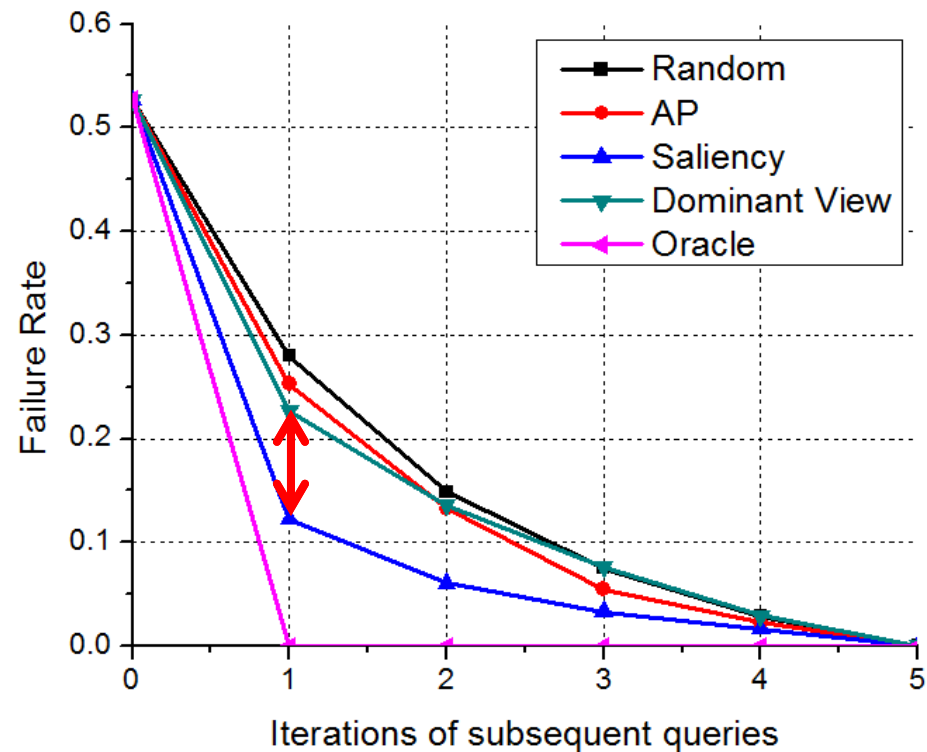
Query Set for Evaluation

- Manually cropped queries from Google Street View
 - 226 random locations
 - For each location: six query images are cropped from viewing angles similar to the view orientations used in the database
- A returned reference location is considered relevant
 - if it has **visual overlapped view** with the query image

Evaluation

- Baseline
 - Random view suggestion
 - Dominant view suggestion
 - Always change to front view
- Salient view selection
 - AP based
 - Saliency based
- Oracle view suggestion
 - Always suggest the ideal view

- Overall Performance



Failure rates over successive query iterations.

Examples

First query



AQS suggested query



First query



AQS suggested query



Outline

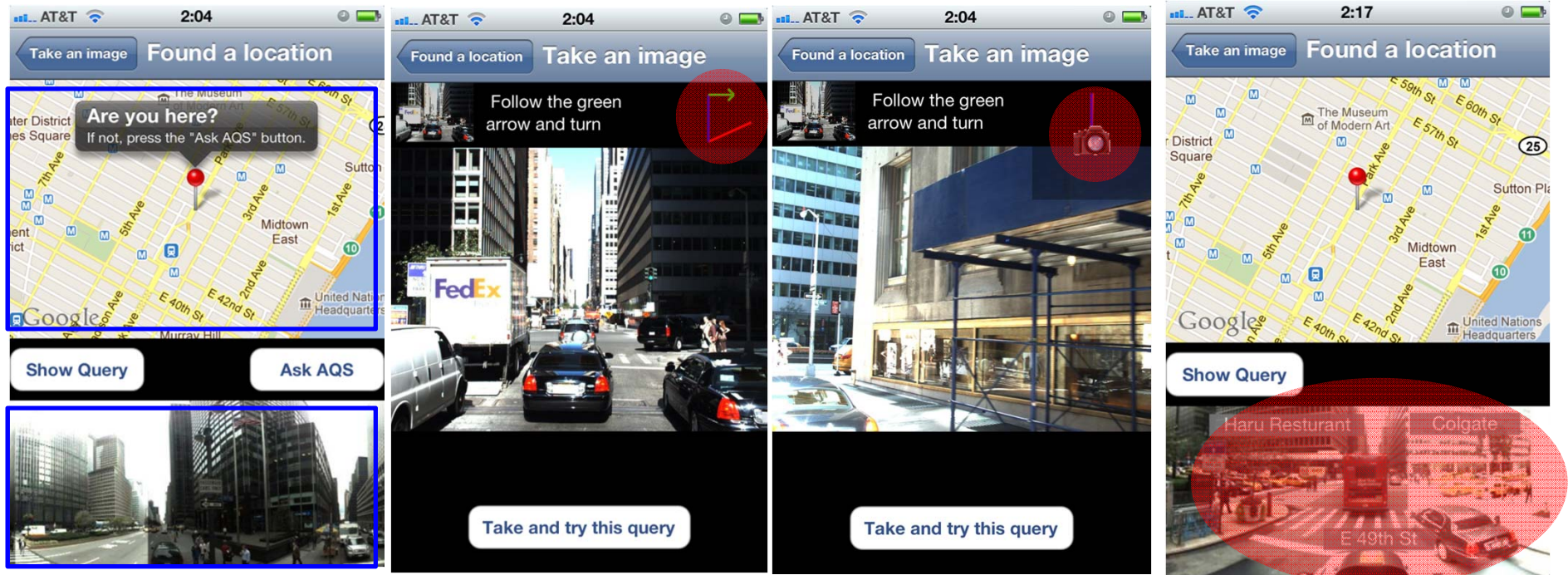
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User Interface

- We have developed an iPhone application of the proposed AQS system
 - The client communicate with the server through wireless network
- Time
 - Visual matching requires $<1s$
 - Query sensing suggestion is almost in real time
 - Query delivery latency depends on wireless link

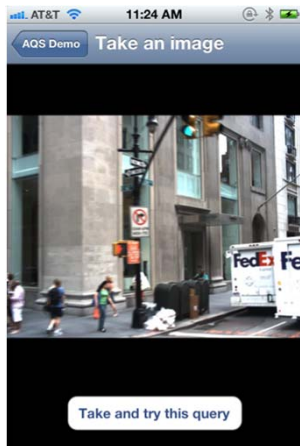
User Interface

- How does the user know the first query is incorrect
 - Panorama
 - Geographical map context
- How to guide the user to take the second query
 - Compass, camera icon
- Point of interest

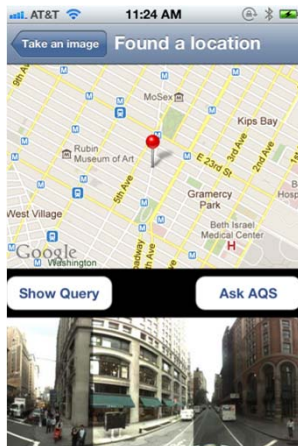


AQS Examples

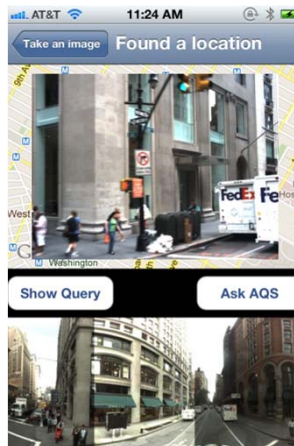
First Query



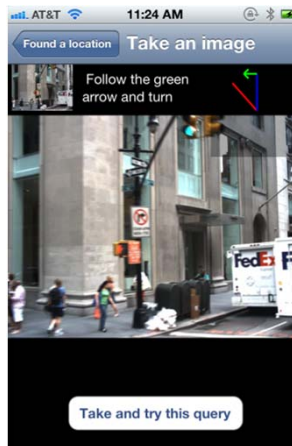
First Result



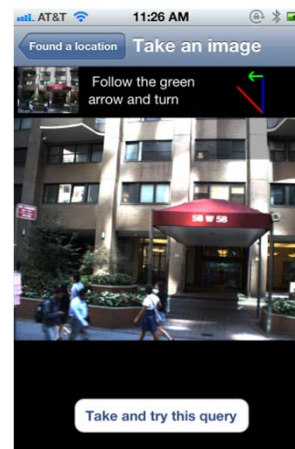
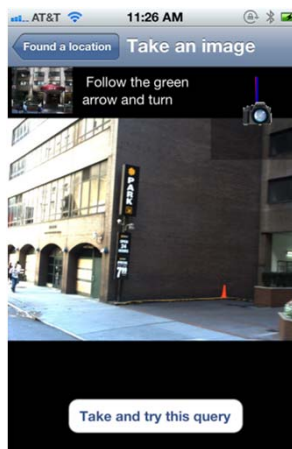
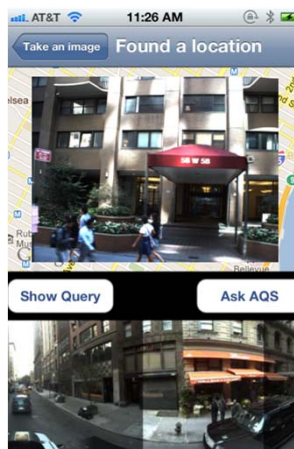
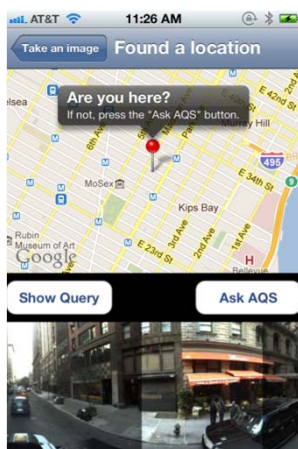
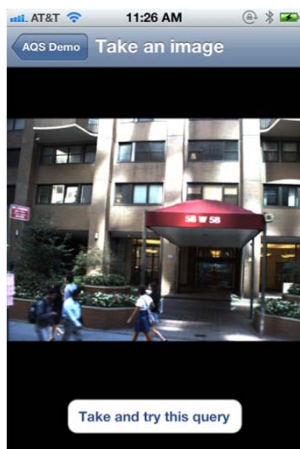
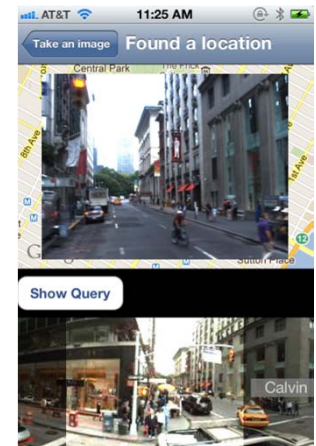
Ask AQS



Taking Second Query



Second Result



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Conclusion

- We have designed the AQS system to
 - Intelligently guide user to take the second query without repetitive trial and error
 - Reduce the error rate from 53% to 12%
- The proposed approach is general. It can be extended to multi-view object search
 - If the database has multiple views of products, AQS can be used to suggest best view for searching



- We have demo about AQS on [Thursday Morning Demo Session](#)



Thank you

Any Question**S**?

We would like to also thank NAVTEQ for providing the NYC image data set, Dr. Xin Chen and Dr. Jeff Bach for their generous help.